

CFD Modeling of Wind Tunnel Flow
over a Rotating Cylinder
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I hereby certify that this is my own and original work,
and that all references have been cited.

signed

John Middendorf

Flow over a Rotating Cylinder

Background

Viscous flow over a rotating cylinder is an interesting problem in fluid dynamics. The rotation of a no-slip cylinder wall creates a pressure gradient which in turn creates lift. The pressure gradient can be explained simply by Bernoulli's principle, in which pressure and velocity are inversely proportional. The phenomena of a rotating cylinder's lift is known as the Magnus effect, named after a 19th century German engineer, and is related to the circulation around an object in a flow field. Rayleigh studied the lift of a rotating cylinder for an inviscid ("frictionless") fluid, and related lift to the circulation of a rotating cylinder by the following formula:

$$L = \rho U \Gamma \quad \text{in which the circulation, } \Gamma, \text{ is given by:}$$
$$\Gamma = \oint \mathbf{v} \bullet d\mathbf{l} = v(2\pi R) = \omega R(2\pi R), \text{ therefore,}$$
$$L = \rho U (2\pi \omega R^2)$$

The relationship between lift and circulation is known as the Kutta Joukowski relationship and applies to all shapes, particularly to the aerodynamic shapes such as an airplane wing.

In a viscous fluid, like air, the cylinder is subjected to both pressure and viscous forces, and the explanation is more complex. Studies (Smith, 1979) indicate that the circulation does not result from the common explanation of the air set into an opposing rotation by the friction of a no-slip wall, as this only occurs in a very thin boundary layer next to the surface. But this motion of the fluid in the boundary layer does affect the manner in which the flow separates from the cylinder. Boundary layer separation is moved back on the side of the cylinder that is moving with the fluid, and is moved forward on the side opposing the main stream. The wake then shifts to the side moving against the main stream causing the flow to be deflected on that side, and the resulting change in free stream flow creates a force on the spinning cylinder.

Problem Statement and Parameters.

A cylinder 0.66m in diameter ($R=0.33$) is modeled as a wind tunnel test. Two parameters for the wall boundaries were modeled in the different grids created, one with walls at $6R$ above and below the wheel boundaries, giving a total height of the wind tunnel as 4.62 meters, and the other (for some of the later CFD models) using a height of $6R$ from the center, giving a total height of the wind tunnel at 4 meters. Using Fluent, the problem was analyzed in two dimensions, which in effect models an infinite width cylinder. The cylinder is rotating at 168 radians/sec, and the windspeed flow in the wind tunnel is 200 km/hr (55.6m/s). There are two Reynolds Numbers of interest: one is the Re of the cylinder, which is:

$$Re_{cylinder} = \frac{\rho U D}{\mu} = \frac{1.225 \text{ kg/m}^3 \times 55.6 \text{ m/s} \times 0.66 \text{ m}}{17.9 \times 10^{-6} \text{ Ns/m}^2} = 2.51 \times 10^6$$

The other Reynolds Number of interest, used for turbulence parameters is the free stream Reynolds number, given by the characteristic length of the wind tunnel (using the 4 meter wind tunnel height parameter):

$$Re_{tunnel} = \frac{\rho U D}{\mu} = \frac{1.225 \text{ Kg/m}^3 \times 55.6 \text{ m/s} \times 4 \text{ m}}{17.9 \times 10^{-6} \text{ Ns/m}^2} = 1.52 \times 10^7$$

Boundary Conditions of Wind Tunnel

It is important to accurately represent in the computational model the free stream flow in the wind tunnel by the choice of an appropriate length. Since CFD is driven by boundary conditions, where the property values of all the elements inside the BCs are essentially “filled in” to attain an equilibrium solution, the placement of the inlet and outflow affects the solution. The inlet boundary is set far enough in front of the cylinder so as to represent fully developed flow by the time the flow reaches the cylinder (since the inlet will be set at a initial velocity, constant for all values). The modeled developed flow when it reaches the cylinder will vary from the inlet boundary conditions because the no-slip wind tunnel walls will slow the velocity near the wall boundaries, affecting also the modeled turbulence as the flow approaches the cylinder. Ten times the diameter of the circle was chosen as a minimum inlet distance in the CFD models.

The outlet boundaries also need to be far away from the point of interest, but for additional reasons related to the assumptions of the solution process. CFD models have two main types of free flow outlet boundary settings: outflow, and pressure outlet (generally constant pressure). Pressure outlet boundaries are used to define the static pressure at the outlet, and are recommended with compressible flow problems. Outflow boundary conditions are used when details of the flow velocity and pressure are unknown prior to solution of the flow problem, and assume a zero gradient for all variables except pressure. Outflow BCs are only appropriate when exit flow is in a fully developed condition. For this to occur after a turbulent wake, at least ten times the diameter of the object causing the wake is recommended (Versteeg and Malalasekera, 1995). The outflow BC was used, and values of at least twenty times the diameter of the circle was chosen for the outlet boundaries.

The initial inlet flow of the wind tunnel is not known completely, but it was assumed that there pre-exists a specific amount of turbulence in the flow field. The computational algorithm uses parameters that are related to the creation and dissipation of turbulence. Some, like the Intensity and Length scale parameters, are based on the assumption that the characteristic velocity and the characteristic length of the larger turbulent eddies in the solution are of the same order as the velocity and length scale of the mean flow, a major assumption of CFD turbulence models. Wind tunnel flows vary in their turbulence characteristics, with turbulence intensity factors being as low as 0.05%. Intensity and length scales can be based on fully developed duct flow by the formula and approximate relationship below:

$$I \cong 0.16(\text{Re}_{D_x})^{-1/4} = 1.99\% \quad l = 0.07L = 0.07(4m) = 0.28$$

which gives values of k and e of:

$$\kappa = \frac{3}{2}(U_{avg} I)^2 = 1.83 \quad \epsilon = C\mu^{3/4} \frac{k^{3/2}}{l} = 1.45$$

The choice of these turbulence parameters are used for the inlet BC's and will change as the model solves. The converged solution should be independent of the initial values, yet it is important to start with reasonable values for the k and e, as it affects the downstream flow. Other turbulence factors can be derived from these numbers, including the Modified Turbulent Viscosity and the Specific Dissipation Rate (used for K-omega models).

Another, separate, parameter used to define the turbulence in CFD models in the Turbulent Viscosity ratio. This ratio is directly proportional to the turbulent Reynolds number, which is defined in terms of the turbulent kinetic energy, the dissipation rate and the viscosity, and is usually in the range of a value between one and ten.

Each one of the turbulent initial boundary conditions has assumptions which relate one to another, and is a source of error. Some, like the relationship between the turbulent dissipation rate and the length scale are based on empirical constants. To accurately model a wind tunnel situation these initial turbulence values would need to be calculated from empirical data to obtain accurate results. Fluent recommends for wind tunnel situation in which the model is mounted in a test section downstream of a mesh screen of using a value of ϵ based on the decaying turbulence in the length of the wind tunnel. If we assume that turbulence decay (for the main flow) to be 10% in a 20 meter wind tunnel, we get an approximate value for ϵ to be:

$$\epsilon = \frac{\Delta k U_{\infty}}{L_{\infty}} = \frac{.1(55.6)}{20} = 0.278$$

which eliminates the need for the length scale assumption based on the hydraulic diameter. Using this method, it is important to check turbulent viscosity ratios to ensure they are not out of range. Another

way is to specify the initial guess for ϵ so that the resulting eddy viscosity $(C_{\mu} \frac{k^2}{\epsilon})$ is sufficiently large in comparison to the molecular viscosity, and base the value for ϵ on the rule of thumb that the turbulent viscosity is roughly two orders of magnitude greater than the molecular viscosity. As can be seen, the range in which the initial turbulence values vary, based on assumptions, is considerable. It is possible that the turbulent initial conditions should be set at the scale of the cylinder, in which case the length scale would be on the order of 0.66m x 0.07. Initial runs, were, in fact run with this figure.

The effect of the wind tunnel walls.

The wind tunnel walls were models as the standard no-slip WALL type boundary in Fluent. They were quite close to the cylinder, computationally speaking, and have an effect on the solution both because of the way the solution computes, as well as the differences between bounded and unbounded flow. Since our model is modeling bounded wind tunnel flow, it is important to model the wind tunnel walls quite carefully with enough grid points to accurately model a boundary condition that reflects a no-slip wall velocity profile. In my earlier grid models, this was not done to the precision required for this problem and is likely a major source of error. Checking the effects of the walls is done by changing the boundary condition for the top and bottom walls from WALL to OUTFLOW, and can be seen in the last part of the results.

Grid

Gambit was the preprocessor used to create the geometry and the grid. Both triangular and quad meshes were created, in total over 15 grids of varying dimensions and element types. Problems became immediately apparent with a poor grid, namely immediate high y^+ values at the boundaries. In the results following, it was clear from the high y^+ values (on the order of 1500-3500) that even my finest grid was too coarse in the boundary layers. The aspect ratio can be a source of error when the longer side of an element is facing the direction of flow; it is preferable to have elements with a large aspect ratio with the short side facing the flow. The other factors that are important to consider when creating a grid are the skew, and the gradient from one element to another. For proper turbulence modeling, opinions differ, but a gradient of 5% (change in size from one element to the next) should be adequate. More comments regarding grid types and geometry can be found in the results. It was helpful to check the grid in Fluent, and reordering the domain sped things up significantly, especially for the models which had multiple faces. The ideal quad grid for this problem has very fine resolution at the circle and fine resolution at the wind tunnel wall boundaries. Spacing of mesh points in between the wall and the circle can be larger. Similarly, to minimize excessive grid points, the spacing of mesh seeds behind the circle could grow to create elements with very long aspect ratio which, aligned with the flow, should solve adequately.

Grid Convergence.

It is possible to use the results from successively finer grids to calculate the error resulting from the grid. Grid convergence calculations on a sequence of grids based on results pages 16 and following are presented here:

<i>Grid</i>	<i>Number of Nodes</i>	<i>Functional (-)</i>	<i>Functional</i>
Medium	31368	Lift=1024.7	Drag=960.1
Fine	47095	Lift=1179.2	Drag=930.2
“SuperFine”	97096	Lift =1278.5	Drag=908.0

The refinement ratio between the grids is given by

$$r_{\text{fine-medium}} = \frac{47095}{31368} = 1.5 \quad r_{\text{superfine-fine}} = \frac{97096}{47095} = 2.1$$

and the relative errors:

$$e_{\text{fine-medium}}(\text{lift}) = \frac{1024.7 - 1179.2}{1179.2} = -0.131$$

$$e_{\text{superfine-fine}}(\text{lift}) = \frac{1179.2 - 1278.5}{1278.5} = -0.0777$$

The grid convergence indexes using the fine and the medium grids are:

$$GCI_{\text{fineGrid}} = \frac{3(0.131)}{1.5^2 - 1} = 0.3144$$

$$GCI_{\text{mediumGrid}} = \frac{3(0.131)1.5^2}{1.5^2 - 1} = 0.707$$

The grid convergence indexes using the fine and superfine grids are:

$$GCI_{\text{superfineGrid}} = \frac{3(0.0777)}{1.5^2 - 1} = 0.186$$

$$GCI_{\text{fineGrid}} = \frac{3(0.0777)1.5^2}{1.5^2 - 1} = 0.419$$

Using these estimate we can estimate the error in our solutions due from the grid, we find the value for lift for the superfine grid is in about 18% error due to grid parameters.

CFD MODELING AND PARAMETERS

General

CFD models solve fluid problems with five basic equations of state:

- Mass conservation (continuity)
- x,y,z momentum equations
- Energy equations

Among the unknowns are density, pressure, temperature, and internal energy. Additional relationships among the variables are derived from the Navier-Stokes equations, in which the viscous stress components are integrated with the momentum equations. For the rotating cylinder problem, we assume that the fluid (air) is behaving as an incompressible fluid at constant temperature (since the Mach number is low), and therefore do not need the energy equation. The results following only use the mass conservation and momentum equations of state.

For turbulent modeling, additional transport equations are used to account for time averaged fluctuations in the local fluid velocities that occur with turbulence, which give rise to additional stress on the fluid, the Reynolds stresses. Reynolds stresses create 6 more unknowns in the equations (three additional unknowns for 2D problems), and are accounted for by additional approximated equations, depending on the model.

Discretization

The solution process depends on solving partial differential equations. CFD uses a control volume technique to convert the PDE's into algebraic equations that can be solved numerically, resulting in a solution which satisfies the governing equations in every element in the grid. Fluent uses a upwind/central differencing scheme, in which the convection terms are solved using upwinding, and the diffusion terms are centrally differenced. First order upwind schemes assume that the cell center values of the variables represent the cell-average value and the face values of the control volume have the same value. Second order schemes include the second order term of a Taylor series expansion of the PDE's, and are more accurate. Fluent also offers the QUICK Scheme which are based on averaging the second order upwind and central differences of a variable. The QUICK scheme is recommended for structured quad grids which are aligned with the flow direction.

Convergence and Under Relaxation

The model is considered solved mathematically when the values in the entire grid are “converged” and do not change significantly from one iteration to the next. The change in value is known as the residual. Depending on the model chosen, the necessary residual levels for convergence varies. First order schemes generally converged adequately when the residual level was set at 0.001, while the second order schemes required a lower residual value, not necessarily at 0.0001 but somewhere in between. There are no hard and fast rules relating convergence to the residuals; for example, if the initial conditions are initialized at the values close to the final solution, there will be small residuals; likewise, if the initialization is very different from the final solution, there will be a larger drop in residuals. Generally convergence level was monitored by the slope of the residual plot, and by looking at the change of a functional. When the functional value stabilized to a certain value, then convergence was likely. This can be monitored visually by turning on the plot forces charts.

Sometimes models converge very slowly, in this case, it is possible to change the under relaxation factors of the solution process. This needed to be done somewhat carefully, as the solution could seemingly converge quicker with higher under relaxation factors. For some models, like the Reynold's Stress Model, Fluent recommends lowering the under relaxation numbers dramatically, from the defaults (on the order of 0.7) to 0.2 or 0.3. Fluent also recommends using residual levels of 0.0001 for the RSM.

Near wall treatments and boundary layer approximations for turbulence models.

In free stream flow, where Reynolds numbers are high (on the order of 100,000 to 10,000,000), the inertia forces in the fluid are much greater than the viscous forces, and the equations are solved on the basis of small viscous components. However, at wall boundaries, where velocities approach zero, the viscous forces will be equal in order of magnitude of the inertia forces, or even larger. Therefore, a separate calculation is required for such regions which include the effect of the viscous forces. A boundary layer can be sub divided into 3 parts:

Viscous sublayer: the layer closest to the wall where viscous effects dominate and the flow is laminar (as turbulent eddying motions must stop in layers where there is no velocity).

Transition layer: where both viscous and inertia effects are considered.

Outer layer: where inertia forces are dominant and the flow is turbulent.

In CFD models, the measurement which determines the layer region (and thus the specific calculations that are performed) is the value known as y^+ , which is a dimensionless value based on the values of density, viscosity, shear stresses due to velocity, and the distance from the wall ($y^+ \equiv \rho u_t y / \mu$). For low values of y^+ ($y^+ < 11.225$ in Fluent), the flow is modeled as laminar. For the transition layer, with mid range values of y^+ ($30 < y^+ < 60$), the flow is modeled as turbulent where viscous forces are included in the calculations. Shear stresses are assumed constant in this region and equal to the wall shear stress. The outer, turbulent layer is modeled with inertia forces as dominant in the CFD calculations, and direct viscous effects are ignored.

Fluent uses two equations to calculate the wall shear stress based on the value of y^+ . If the value of y^+ in the cell adjacent to the wall is within 11.225, Fluent uses the laminar stress strain relationship:

$$\frac{u}{u_t} \equiv u^+ = y^+$$

If the value of y^+ is greater than 11.225, then fluent uses the Law of the Wall equation to solve the flow for the cell adjacent to the wall boundary:

$$u^+ = \frac{1}{\kappa} \ln E(y^+)$$

where κ and E are constants based on empirical data. E is related to wall roughness.

In modeling with CFD, it is important to ensure that the grid is fine enough at the wall boundaries to ensure that the y^+ values are not too high, as it is in this region where the CFD programs include viscous shear stresses in the calculations. The y^+ values at the wall boundaries is marginally affected by the choice of model (which may vary in their calculations of turbulent viscosity), but the main factor that affects the y^+ values is the mesh. Generally, the first thing to do after running a model is to plot y^+ values at the boundary to check to see the range of values. If the y^+ values of the cells adjoining the wall surface are greater than 500 (at best), the results there will be in error, as the program will be including viscous effects in regions of the model that are outside the transition boundary layer. A finer mesh is required in such cases. y^+ values of 60 or less are desired, but note that the maximum allowable y^+ value, where the values of the log of y^+ plotted against u^+ are linearly related, increases as the Reynolds number increases.

Fluent uses two main choices for modeling the wall. The Enhanced Wall Treatment is the preferred model, as it includes reasonable equations for all points in the mesh. It is chosen as an option in fluent, which is somewhat deceiving, since one would assume that solving as accurately as possible with the equations of state and the turbulent equations in every cell would be the default. Fluent recommends having a mesh which results in y^+ values between 1 and 5 in the mesh points adjoining the wall boundary as a minimum, something I did not see as being possible in a mesh of less than 300,000 nodes for our problem. However, Fluent uses a two layer approach which includes a blending term which allows coarser meshes to solve even if the mesh elements adjacent to a wall are not within the inner boundary layers. If the Enhanced Wall Model is used, there is an option to include pressure gradient effects.

The other model Fluent uses is the Wall Functions, and is the default. Wall functions make additional assumptions regarding the transition layer, and when wall function is selected, Fluent does not solve directly for flow in this viscosity affected region, rather, calculations are based on assumptions arising from the linear part of the $\log y^+/u^+$ plot. Still, it is recommended to keep y^+ values close to 30 when using this model, although values up to 500 may be acceptable for high Reynold's number flows. Above these numbers, the wake component becomes larger (where velocities may change direction). The non-equilibrium wall functions option is a variation to the standard wall functions which include pressure gradient calculations, and are recommended for flows which involve separation (although the enhanced wall treatment is more applicable in such flows).

Turbulence models

Various models were utilized to study the rotating cylinder in the wind tunnel, and varied considerably in the results. The total number of choices and sub-choices are staggering. Excluding the variations of the setting of initial conditions, which varied from model to model, as well as excluding energy solution parameters, the total number of turbulent model options exceeds 50, if one includes the choices of wall treatments for each model. Without direct experience with each specific model, it is difficult to choose the best one for our scenario. For example, it is difficult to know on what scale "swirl" is fluid dynamically defined without seeing computational examples of it. Many models were tried, and many failed. The basis of each turbulence model is discussed here.

Spalart-Allmaras Turbulence Models

The Spalart-Allmaras is a one-equation (in addition to the general transport equations) turbulence model which solves for the turbulent eddy viscosity, and eliminates the need to calculate the length scale related to local turbulence. Although designed to be used with meshes that fully resolve the inner boundary layer (i.e., cells with y^+ values of 1-11.25), in which case the enhanced wall treatment option should be selected, it has been shown to be adequate for coarser meshes if the wall function option is chosen. When using this model, the Strain/Vorticity based turbulence production option should probably be used for flows which include separation, as it includes the effects of the mean strain due to rotational velocity gradients. My runs show mixed results with the Spalart Allmaras.

K-e Turbulence Models

The K-e models are the workhorse of the CFD industry, and have been shown to be robust in a variety of applications. K-e models use two equations to calculate turbulent Reynolds stresses, based on calculations of turbulent kinetic energy (k), and turbulent dissipation (e). The k-e model uses additional constants based on empirical data from a wide range of flows. However, although the turbulent kinetic energy can be calculated quite precisely, the dissipation rate is a bit of a fudge, as there are many unknown and unmeasurable terms in the dissipation equations. The basic assumption is that turbulent dissipation is on the same order of the turbulent production term, and the K-e model applies mostly to flows that are fully turbulent, where the effects of molecular viscosity are negligible. The model has

problems with flows that have curved boundary layers, as our rotating cylinder problem does, yet it was used for many of the runs in the results because of its consistent results.

Besides the standard K-e model, two more variations are available in Fluent. The RNG model also uses two equations for turbulence kinetic energy and dissipation, yet has different constants and calculates the effective viscosity differently. It is considered more responsive to flows with rapidly changing strains, and for flows with high streamline curvature. Two options are available with RNG: “differential viscosity”, which accounts for low Reynolds number changes to turbulent viscosity, and is only recommended for grids which are refined in the boundary layer. The other is “swirl dominated flow”, which also affects the turbulent viscosity calculations and used for flows which have significant swirl. When using the RNG model, it is recommended to begin with a solved solution from the standard K-e model, although I didn’t have much luck with this technique. The third K-e model is the Realizable model, which uses a similar equation for turbulent kinetic energy, but calculates turbulent dissipation independent of the rate of production. This makes the model more likely to diverge with a poor model, but is shown to produce better results for flows which include mixing layers and boundary separation. Good results were had with the Realizable model.

K-omega Turbulence Model

The K-omega model also uses two equations to represent the turbulence, but instead of e, it calculates a specific turbulence dissipation rate, which can be considered the ratio of e to k. It is recommended for low Reynolds number flows, and does not offer the standard wall function choices in Fluent, as by default, it uses the enhanced wall treatment methods described above; that is, it solves for near wall treatments when the mesh is fine enough, and uses wall functions when the mesh elements are not placed entirely within the boundary layer. The SST (Shear-Stress Transport) K-omega model takes into account the transport of turbulent shear stress, and makes a gradual change of solution variables from the standard K-omega model in the inner region of the boundary layer to a high Reynold’s number version of the K-e model in the outer part of the boundary layer. The SST K-omega model is more reliable for flows which have adverse pressure gradients, and would be the preferred model, of the two k-omega choices, for modeling the rotating cylinder, as it includes boundary separation. Options for the K-omega model include transitional flows (a low Reynolds number correction to turbulent viscosity), and for the standard K-omega model, shear flow corrections.

Reynold’s Stress Equation Turbulence Models

The most advanced (requiring the most computational resources) classic turbulence model is the Reynold’s Stress Model (RSM), which uses equations to solve directly for the Reynold’s stresses. Five additional equations are involved in the 2D model (seven in 3D), and because it makes fewer assumptions about the turbulent eddy formations and dissapations, it is considered the “simplest” and most accurate of the turbulence models for fluid flows.

Recommendations

The standard K-e model with enhanced wall functions, is the model that seemed to work overall the best for my models, despite its not being recommended for problems due to the high pressure gradients and separated flow. There were also good runs with the K-e Realizable with enhanced wall functions. Other possible models would include the K-omega SST with the transitional flows option, and perhaps even the Spalart Allmaras with the Strain/Vorticity option and with standard wall functions, for the coarser meshes. For a three dimensional model, perhaps swirl would be a consideration on the ends of the cylinder, and would require a model like the RNG with swirl modifications. The RSM model solved occasionally in my runs, but requires better meshwork than I was able to provide. Perhaps it too would be the best choice for a 3D model. Second order descretization is also preferred.

Errors, Validation, Verification

Our goal here was to predict the characteristics of flow over a rotating cylinder in a wind tunnel. The CFD model contour plots give a good indication of the general flow characteristics, however, there are many sources of error, including the 2D assumption, the approximations made in the discretization calculations, the compressibility of the flow (this model is in the subsonic range), the mesh error, the lack of energy modeling, and the assumptions made in the boundary conditions.

Validation

The rotating cylinder problem is modeled as 2D, and assumes an infinite width cylinder, and thus does not take into account flows around the edges that would occur in a real world test. To accurately model the wind tunnel test, a 3D problem would need to be set up. In addition, more precise knowledge would need to be obtained about the actual turbulence conditions in the wind tunnel. The exact temperature and pressure of the flow would also need to be monitored and recorded. The boundary condition set at the outflow is also an assumption (constant pressure). In addition, the cylinder walls are modeled as smooth with default roughness variables. The exact surface characteristics and how they affected the creation and dissipation of turbulence would also require accurate measurement to compare the CFD model with the physical one. From my data, I was getting results which indicate a lift/drag ratio which varied from about 1.6 to 1.1. Empirical data suggests the actual values for lift/drag of a rotating cylinder to be on the order of 1, but perhaps this takes into account edge effects, which would lower the L/D ratio. The theoretical inviscid solution gives lift values of around 7000, my values were on the order of 1200. This is no help in validation, but the drag coefficient of an infinitely long (non-rotating) cylinder is available, which gives a value of approximately 0.6, which is in range of my results:

$$C_d = \frac{\sim 850}{1/2 \rho U^2 D} \approx 0.68$$

Verification

With the results from the CFD models, we can verify the appropriateness of the result by examining the assumptions made in the calculations. The grid errors are discussed above, as well as the quality, which involves the grid size, shape and type. We can also verify the assumptions made in each of the turbulent models, related to how the actual turbulence is created, and what factors are included, as well as the entire CFD process, which, for example, truncates all the third order and higher terms from the Taylor and power series expansion when solving the PDE's. CFD methodology is discussed previously. Looking at the contours, we can verify if the results from the CFD are realistic in terms of the flow characteristics (see discussion following). And of course, the CFD results can be verified by tests done in a wind tunnel if the conditions can be modeled exactly. This would include studying and measuring the boundary layer and moment of separation, pressure distribution along the cylinder walls, and measurements for turbulence around the cylinder.

Summary

CFD is a delicate process of balancing many assumptions to predict real world fluid flows. To accurately model a fluid flow, it is important to have an excellent understanding of the flow features prior to creating a grid and selecting a CFD model, as different models make different assumptions which are specific to certain types of flows. A good understanding of every process in the CFD analysis is vital to obtaining reasonable results, and extensive experience in comparing computed results to experimental tests would be essential for a researcher to have prior to predicting untested flows.

Results and General Flow Features

Please see the next 20 or so pages for results. Pertinent results can be found on the last three pages, from which produced the following plots. Cylinder is rotating counter clockwise in all runs.

General Flow Features

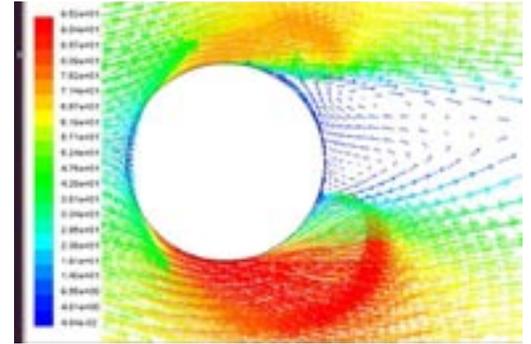
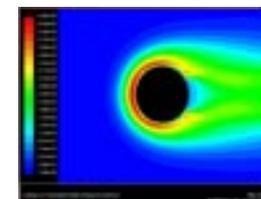
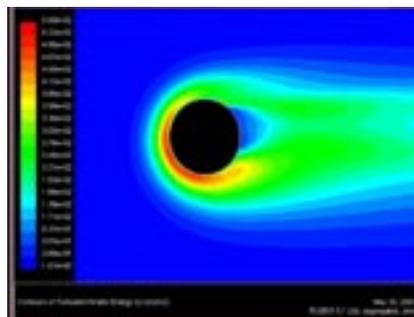
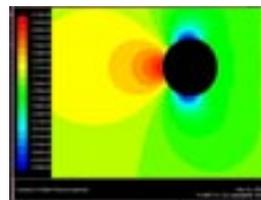
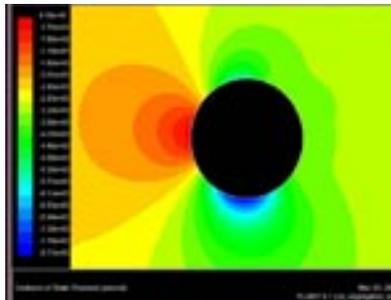
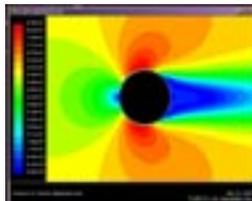
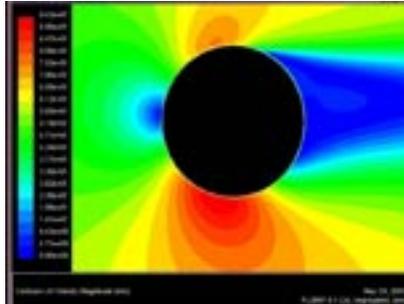
Right: This velocity contour shows a stagnation point at the center front position, and a forward upper separation point and a delayed lower separation point. The wake behind the cylinder is shifted upwards relative to a non-rotating cylinder.

Right: zero rotation velocity contour for comparison

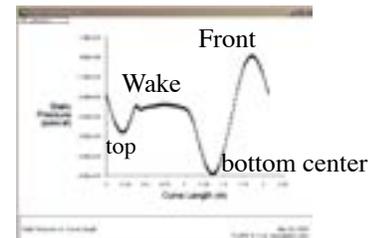
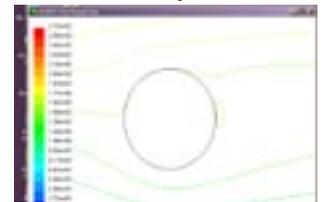
Right: The pressure contour shows a high pressure spot for front center, with a pressure imbalance on the top and bottom center points. The lower pressure area is the greater than the lower pressure area on the zero rotation model, below, while the upper pressure area on the rotating model is higher than the zero rotation model. *Right: Zero rotation pressure plot for comparison*

Right: The turbulence contour plot shows high turbulence along the front edge of the cylinder, with a pocket of lower turbulence in the wake near the cylinder. The displaced wake diverts the main flow, which in turn affects the velocity differential, affecting the pressure imbalance which creates the lift.

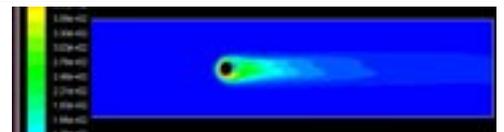
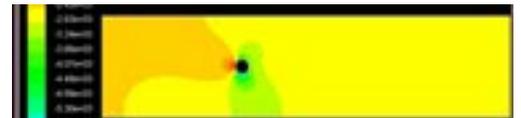
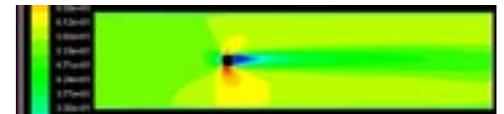
Right: Zero rotation turbulence plot for comparison



Above: Velocity vectors showing the wake pattern of the region behind the cylinder. Below: the velocity streamline plot shows the stagnation and separation points more clearly.



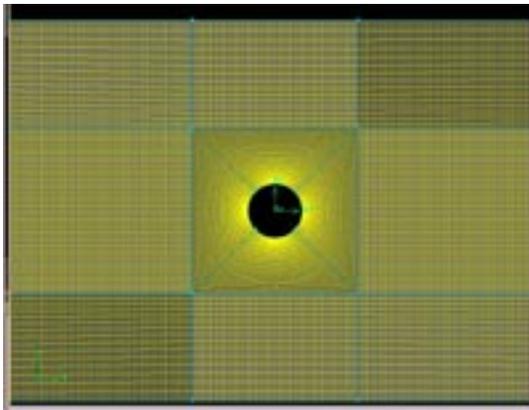
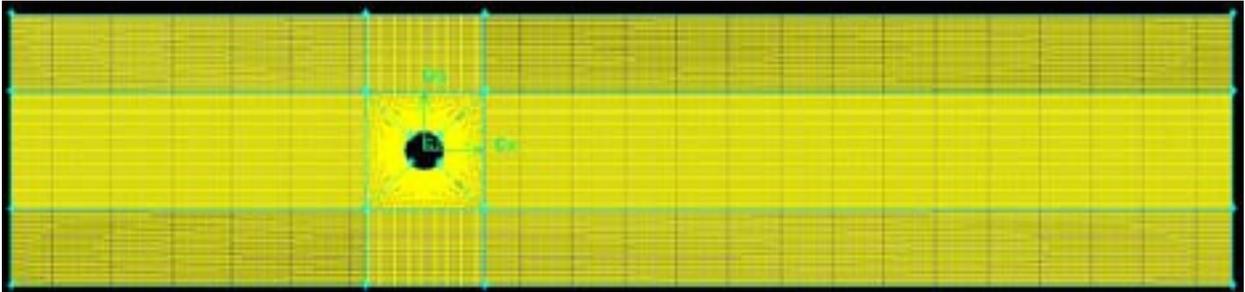
Above: Pressure distribution on the wall of the cylinder. The forward stagnation is the high point of the curve, while the two low points are the top and bottom pressure. The flat area is the wake.



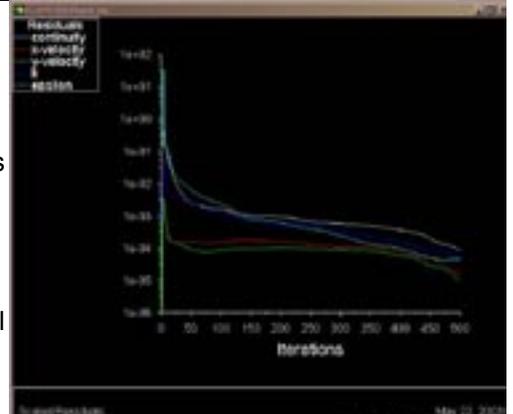
Above right: Contour plots of velocity, pressure, and turbulence. The velocity shows the upper/lower differential, while the pressure plot shows that the gradient reaches the wind tunnel walls. Turbulence in this model diminishes considerably after about 5 diameters of the cylinder.

RESULTS Page 1

Initial Runs with Quad Mesh and standard K e model and second order discretiation. This is where I learned about the proper way to check for convergence.. These tests were run with my initial medium quad mesh (12 faces), which initially had 57073 nodes (200 mesh seeds on circle).



First run converged to .001 residuals after 140 iterations, second with 0.001 residual level at 500 iterations. Left side is 0.001 convergence, right side is 0.0001 convergence. After this I decided to check convergence by examining the residual plat and checking when the residuals level off.

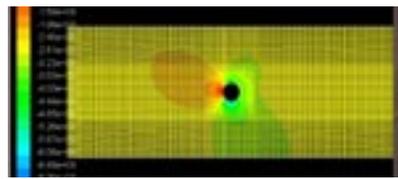
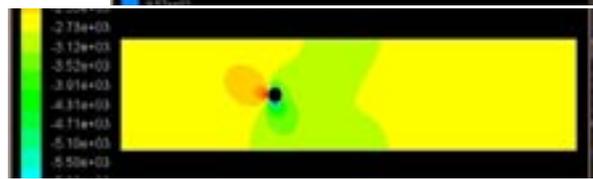
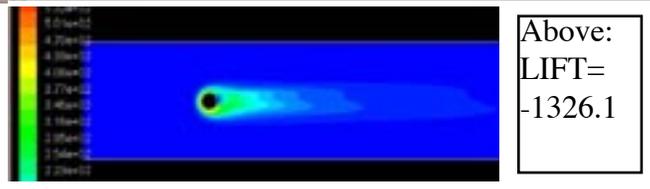
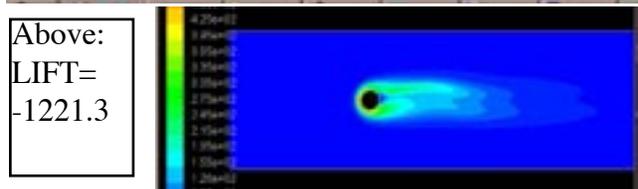


Force vector: (1 0 0)	pressure force	viscous force	total force	pressure coefficient
zone name	#	#	#	#
bottomwall	0	181.4017	181.4017	0
topwall	0	181.86786	181.86786	0
side1a	954.87222	21.545126	976.41735	1558.8767
net	954.87222	224.84699	1179.7191	1558.8767

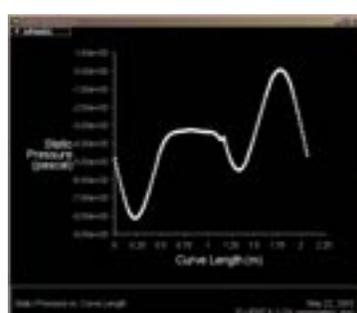
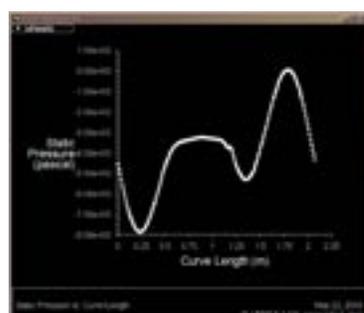
drag= 976.4

Force vector: (1 0 0)	pressure force	viscous force	total force	pressure coefficient
zone name	#	#	#	#
bottomwall	0	182.94816	182.94816	0
topwall	0	188.88623	188.88623	0
side1a	891.48822	21.8659	913.35412	1405.4779
net	891.48822	225.62239	1117.1106	1405.4779

drag= 918.2

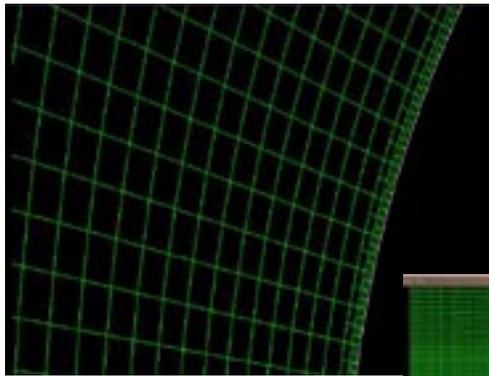


Turbulence, Pressure contour, and pressure on surface of circle for 0.001 convergence level (140 iterations)



Turbulence, Pressure contour, and pressure on surface of circle for 0.0001 convergence level (>500 iterations). Note the more developed turbulent flow contour.

PAGE 2. Next I experimented with Adapted Grids, using both y^+ and boundary adaptation. Later found out that the boundary adaptation process could cause undue effects due to adverse mesh gradients, but the y^+ adaptation worked well (y^+ adaption usually added no nodes after boundary adaption).



Left: Boundary Adapted Grid.
Right: Forces after adapting grid.

force vector: (1 0 0)			
zone name	pressure force	viscous force	total force
	n	n	n
bottomwall	0	182.96816	182.96816
topwall	0	188.88633	188.88633
wheel	891.48822	21.8659	913.35412
net	891.48822	225.63229	1117.1206

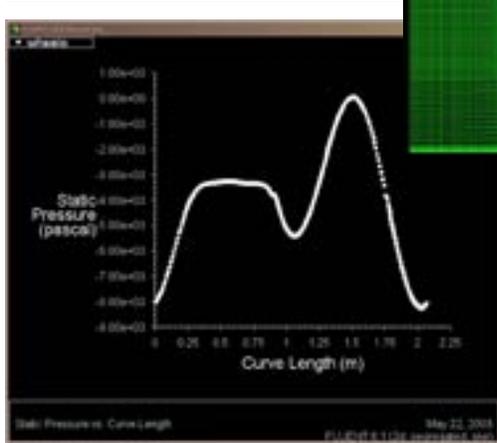
drag = 918.2

force vector: (0 1 0)			
zone name	pressure force	viscous force	total force
	n	n	n
bottomwall	54784.801	0	54784.801
topwall	-52682.145	0	-52682.145
wheel	-1331.8412	5.775723	-1326.0655
net	-158.9547	5.775723	-145.17873

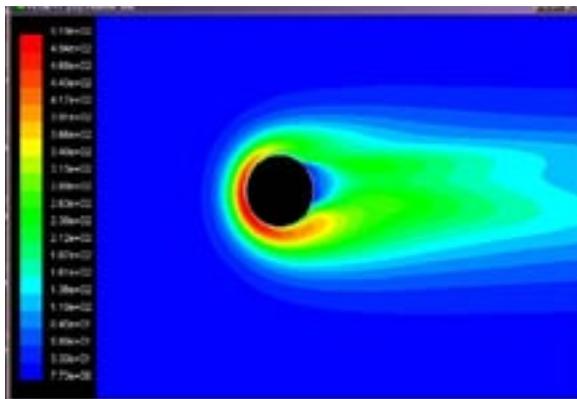
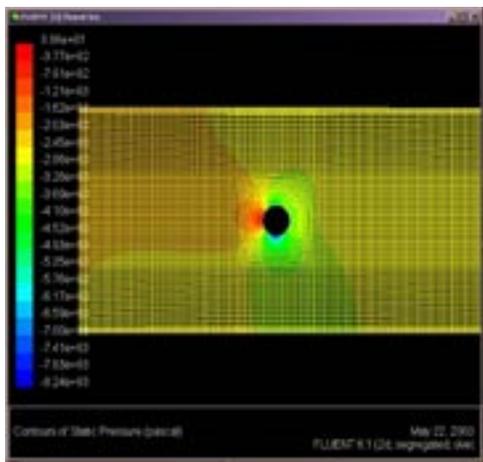
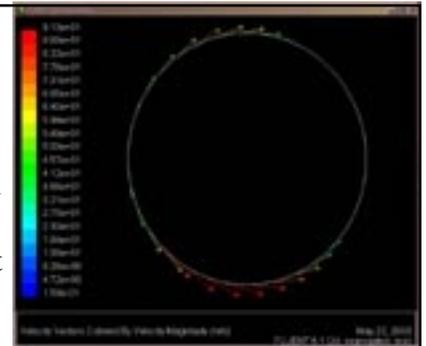
Above: LIFT = -1331.8

Grid size { original / adapted / change }		
cells	{ 53846 / 64806 / 11060 }	
faces	{ 118119 / 135881 / 25762 }	
nodes	{ 57823 / 71795 / 14222 }	

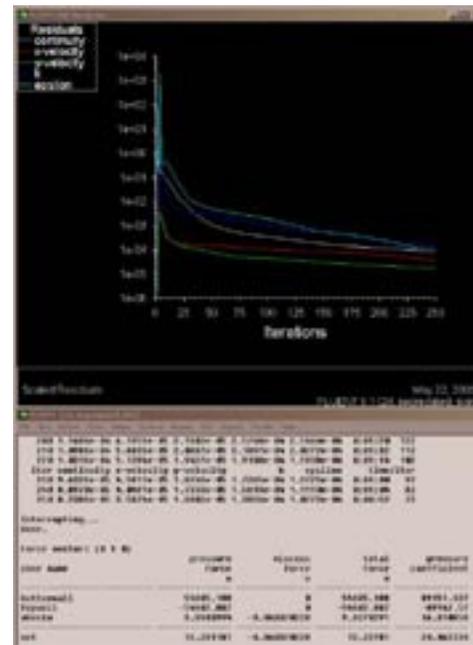
Above: 57073 nodes to 71795 nodes



Right: velocity vectors on the spinning (168 radians/sec) circle. Note the spinning circle does not have enough rotation to counter the oncoming flow, despite the fact that it is a no-slip wall.. This seemed to be independent of the grid size, as after several boundary adaptations, the velocity vectors still did not reverse on the surface of the circle. Yet when the rotation was increased to 1680 radians/sec, the vectors on the top surface did reverse.



Above: various plots after grid adaptation.

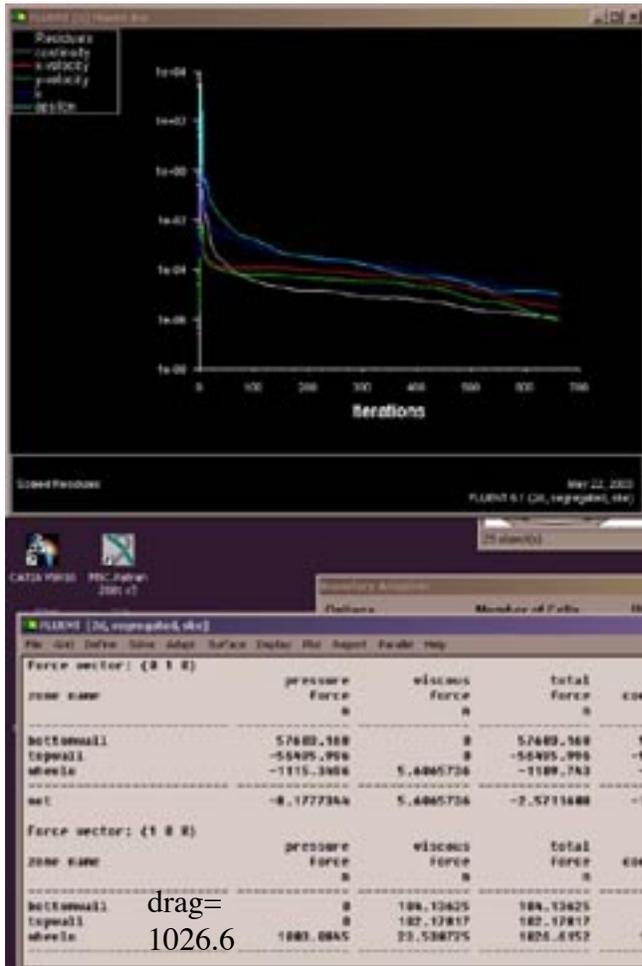


Side Notes

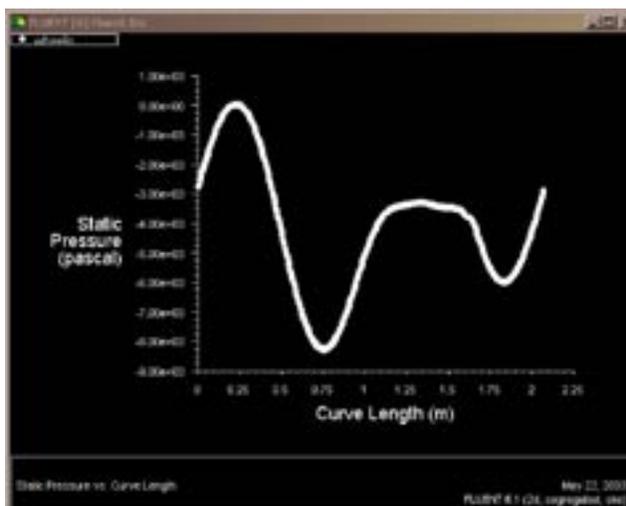
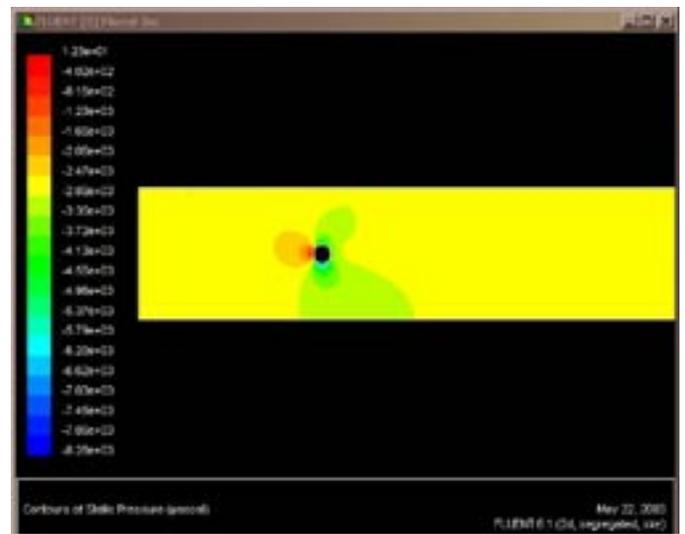
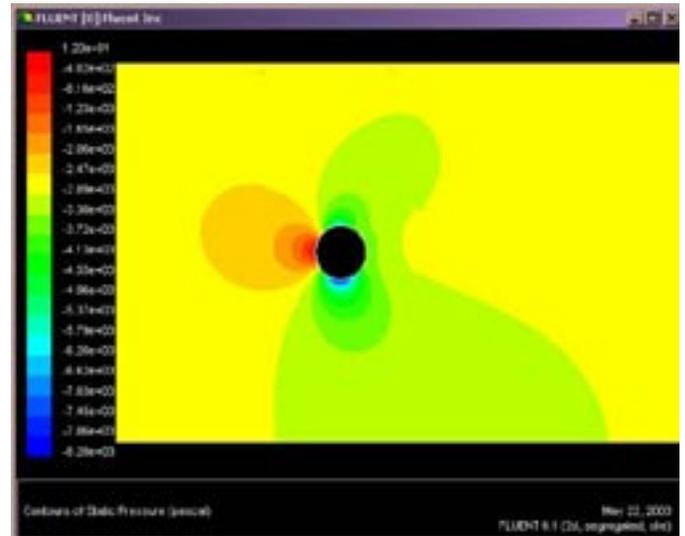
(note: I also ran other models here, including RNG, Reynolds, Spalart-Allmaras, but this was prior to my knowing the correct parameters for them, so the results were bad.

Left: A quick check of forces after a run with zero rotation on the circle. Note lift force error (should be zero) probably due to coarseness of grid. LIFT = -9.027

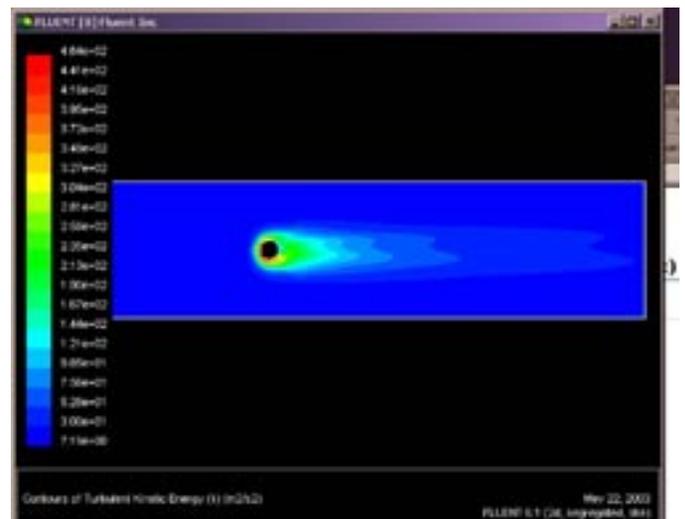
PAGE 3. Next I ran some tests with SIMPLE and first order solutions, with 0.0001 and 0.00001 residual levels. There was no difference between the residual levels. These were with the adapted grid, and the values for the lift were lower than the second order solution.



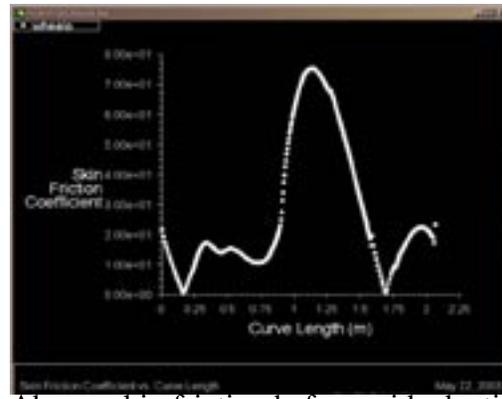
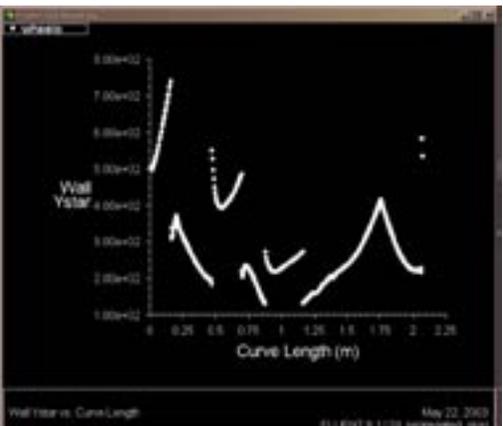
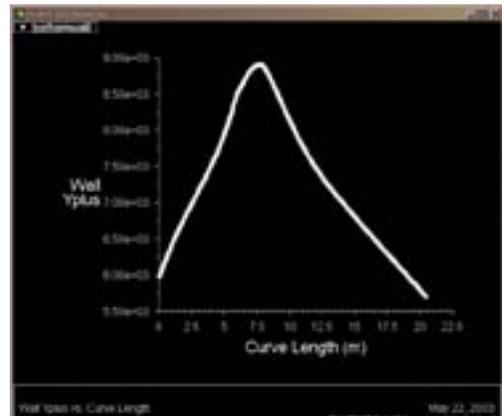
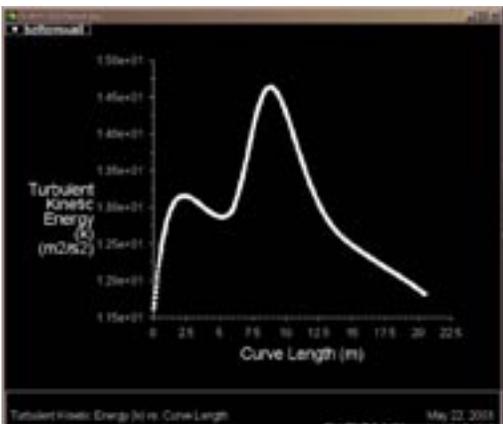
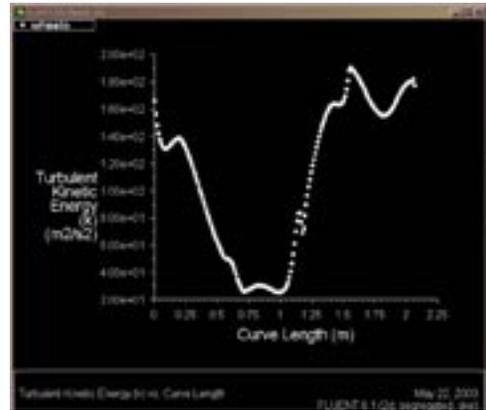
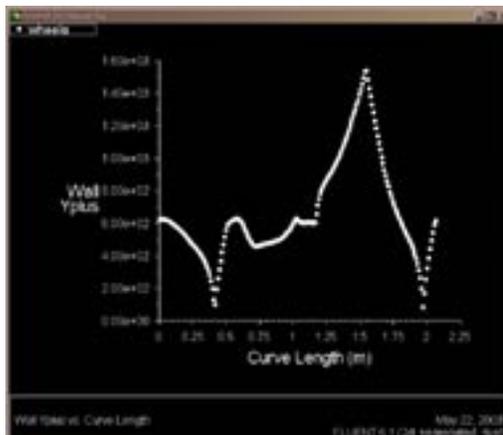
Above: LIFT= 1109.7 (first order solution)



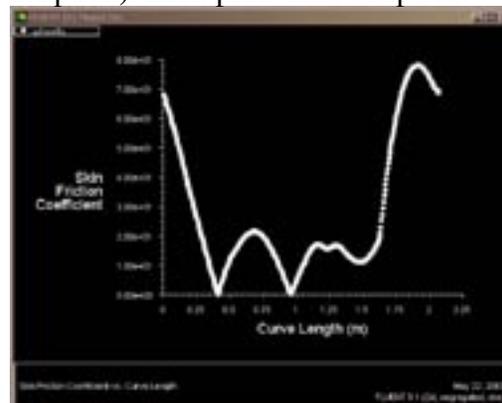
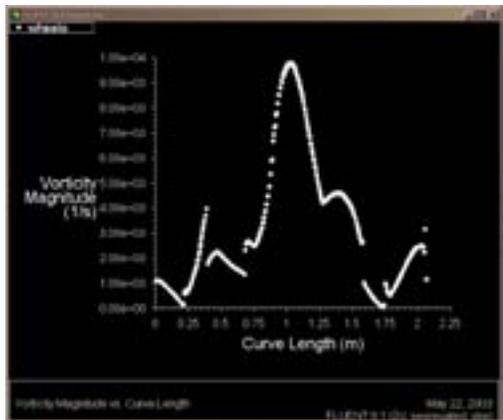
Side note: around this time I also tried a run with the PISO algorithm, but it failed to converge.



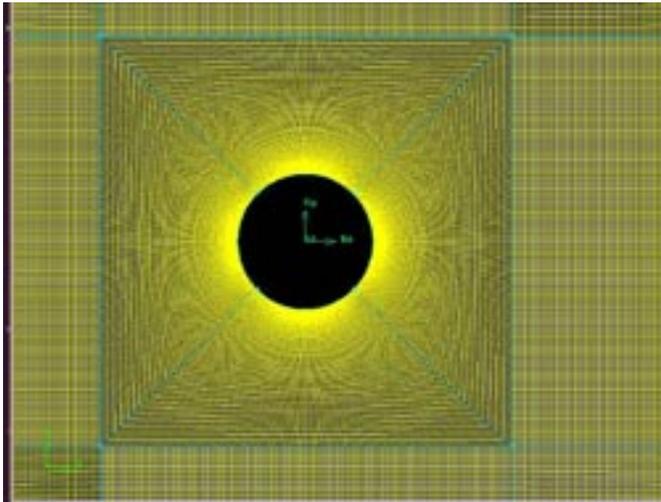
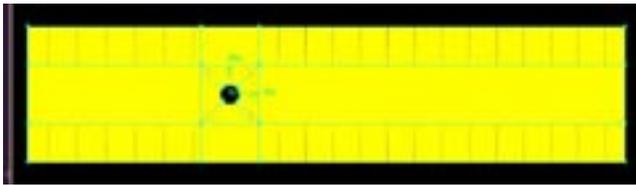
PAGE 4. Below are various other plots of the initial experimental runs with the same Medium Quad mesh.(top four before grid adaption).



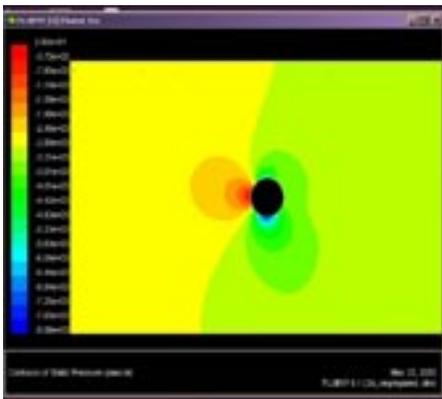
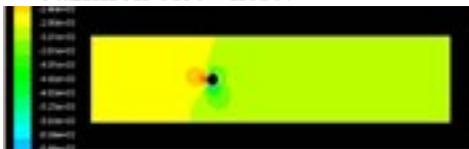
Above: skin friction before grid adaption,
Below: after adaption (nearly identical except the zero point has changed with grid adaption). Left: plots after adaption.



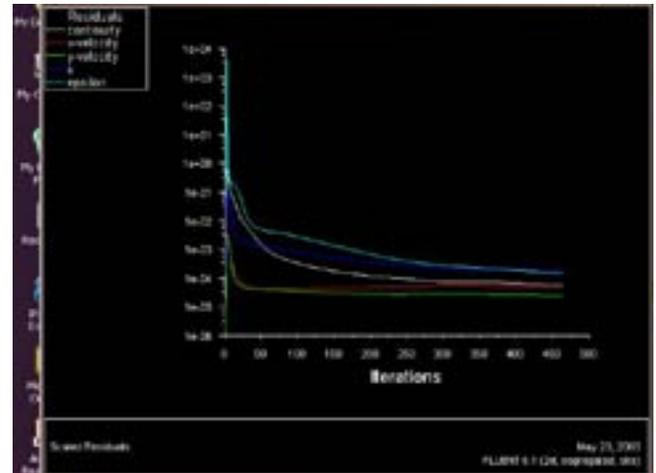
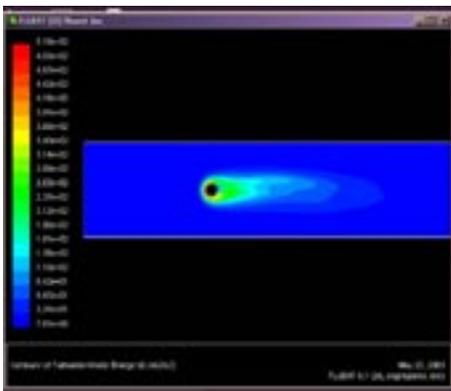
PAGE 5. Next I built and ran a fine mesh, without adaption.. This had 171,597 nodes in its 12 faces and took a ridiculous amount of time to run. (Standard Ke).



Above: mesh with 400 nodes on circle, and a bazillion elsewhere.



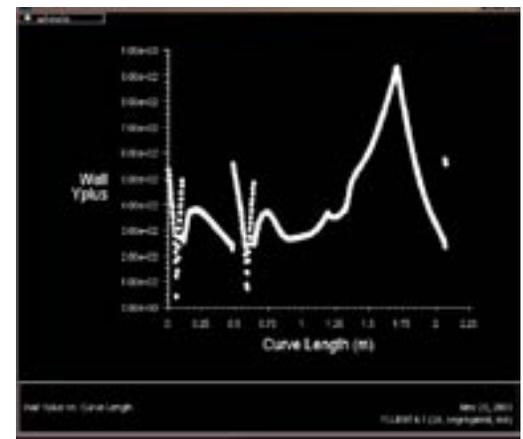
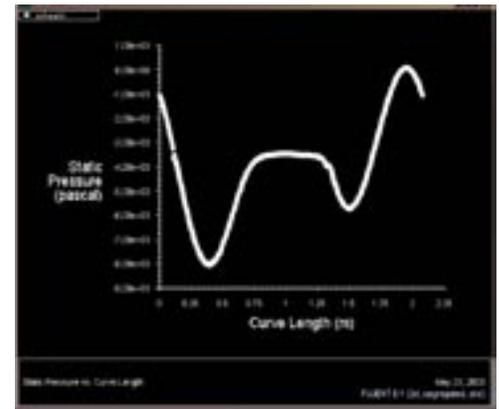
Left and below: pressure and turbulence contours.



Force vector: (0 1 0)					
zone name	pressure force	viscous force	total force	prc coeff	
walls	1297.3711	-2.1272558e-28	1297.3711	210	
wheels	-1119.2650	6.6758986	-1112.4899	-182	
set	178.08525	6.6758986	184.68115	298	
Force vector: (1 0 0)					
zone name	pressure force	viscous force	total force	prc coeff	
walls	0	213.87448	213.87448	163	
wheels	998.48456	22.144859	1020.6294	163	
set	998.48456	225.42134	1223.9059	163	

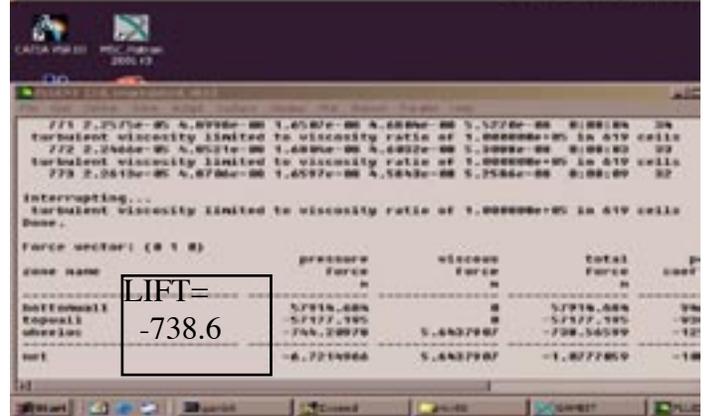
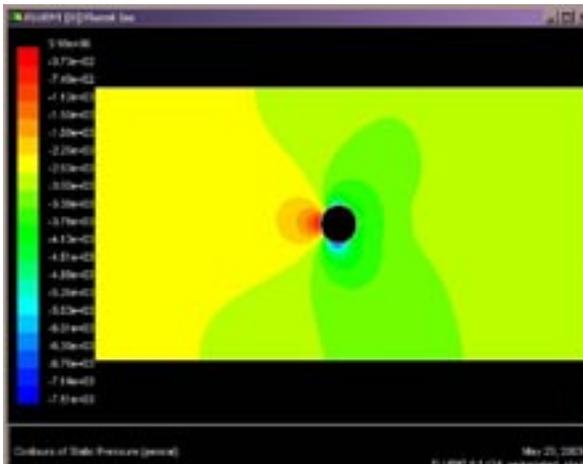
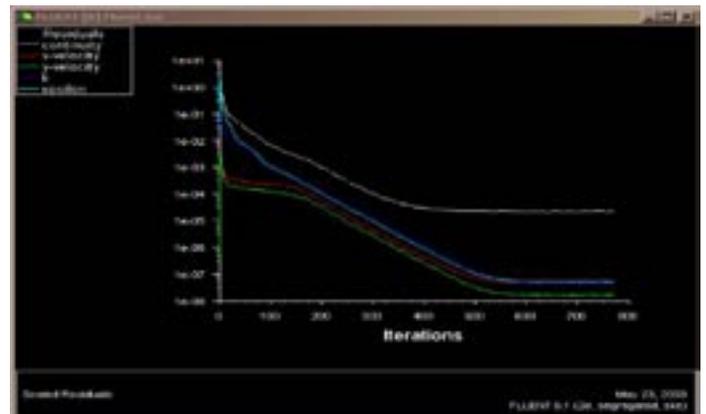
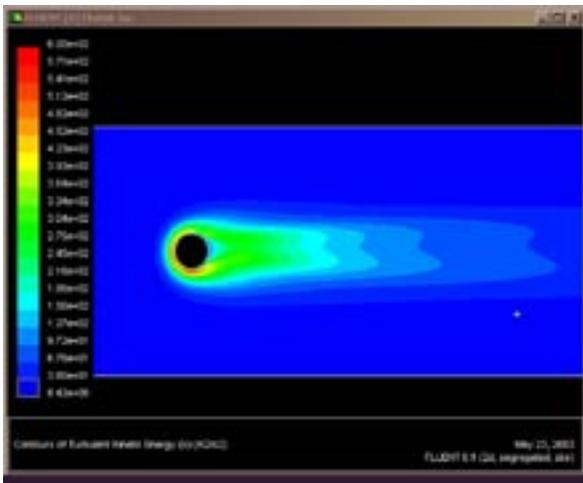
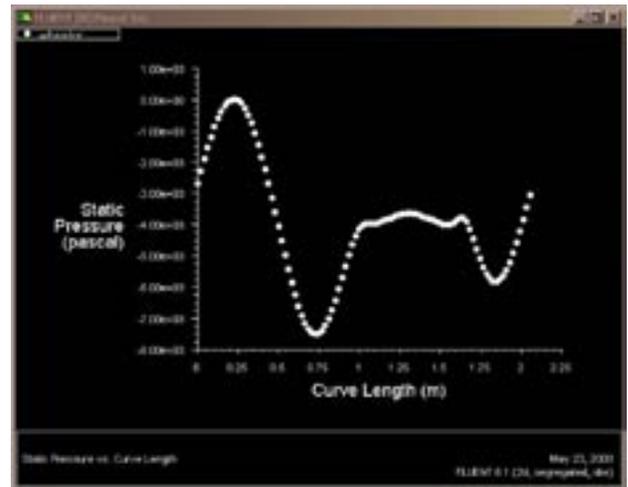
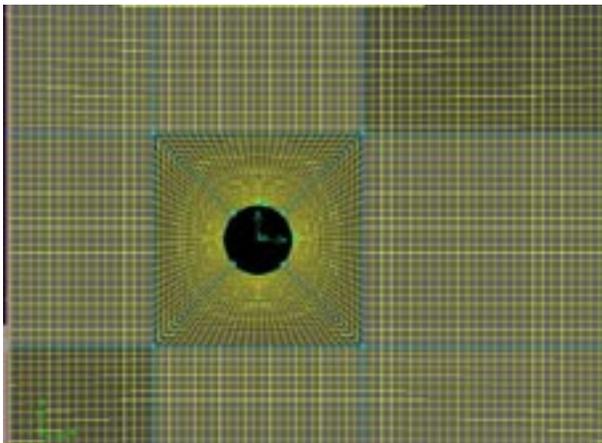
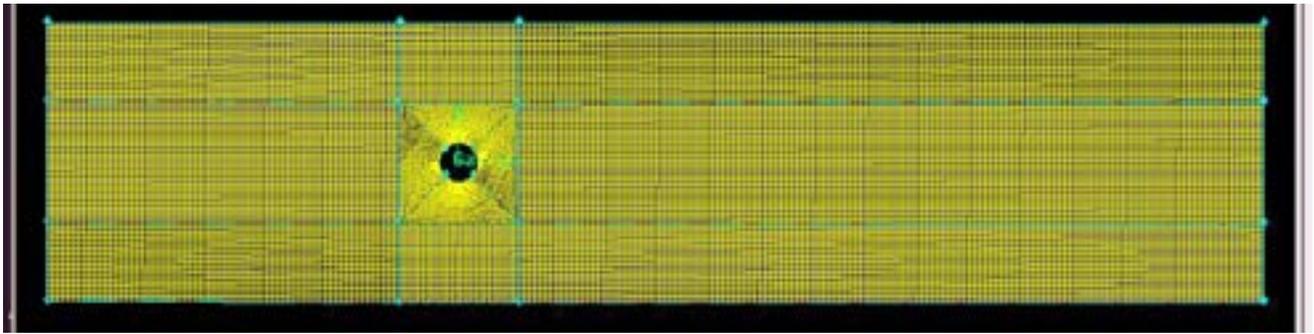
drag=1020.8

Above: LIFT= 1112.7

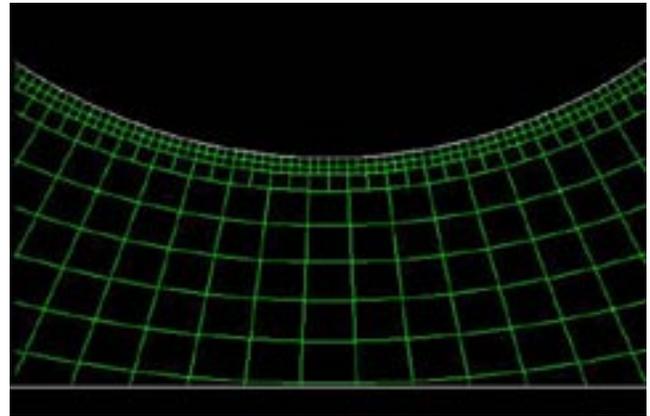
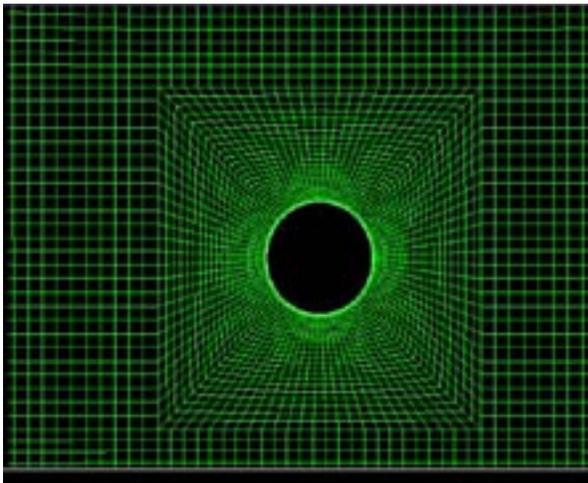


Right: Even with this excessively dense mesh, the y+ values on the wall were still out of range (peak = 1000). Clearly there had to be another way.

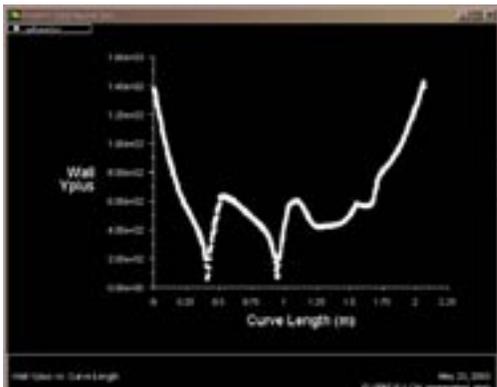
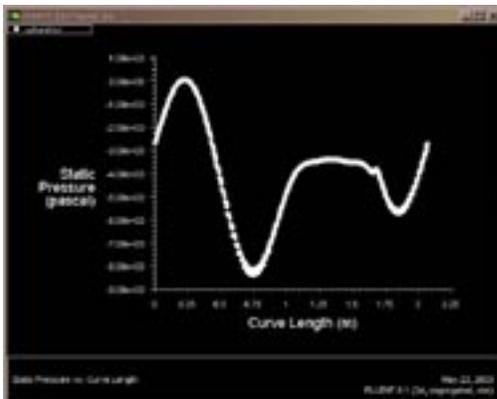
PAGE 6. Next was a coarse quad mesh to do some quick test runs(14560 nodes before adaption). 100 nodes on circle.



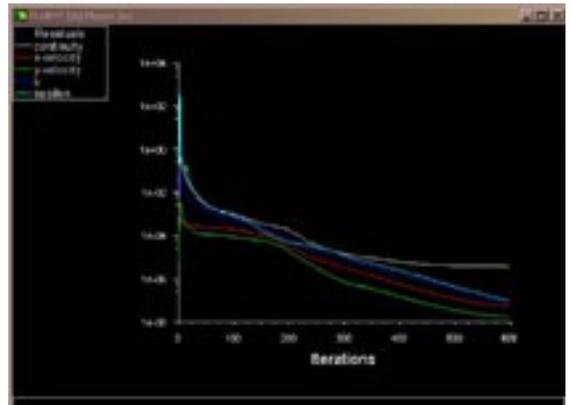
PAGE 7. Same Coarse Mesh after boundary adaption.. Again, this is before I realized that random boundary adaption didn't solve the y^+ problem.



Grid size (original /	adapted /	change)
cells (15905 /	19595 /	3690)
faces (32787 /	41317 /	8610)
nodes (16802 /	21722 /	4920)



Note how the boundary adaption does not solve the y^+ value problem of being too high (max = 1600), yet even with the coarse mesh lift values improve after boundary adjustment.

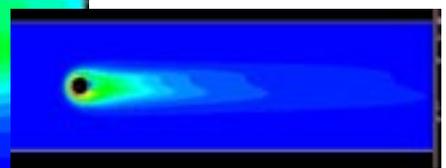
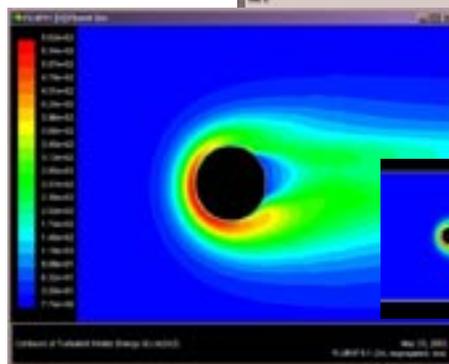
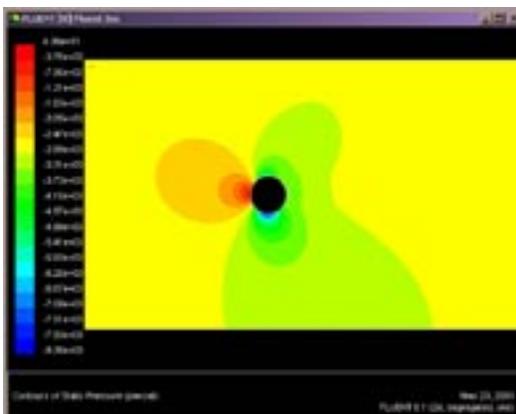


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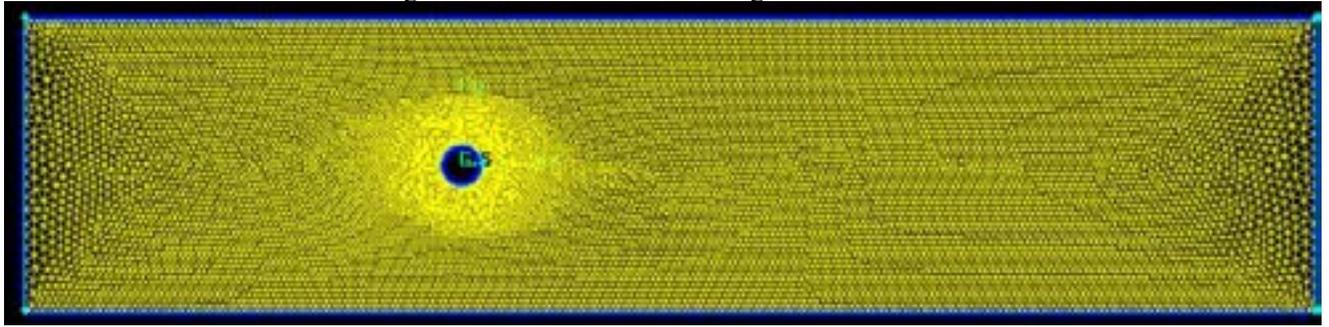
Interpolating....
Turbulent viscosity limited to viscosity ratio of 1.00000e+00 in 627 cells
Done.

Force vector: (R T M)
-----
name      pressure      viscous      total      p
name      N             N             N             coef
-----
lift       5.7988e+02    0              5.7988e+02    0.1
moment    -55861.528    0              -55861.528   -0.1
drag      -1226.1578    5.7745e+03    -4548.8822   -0.8
net       -6.8462169    5.7745e+03    -1.0785736   -1
    
```

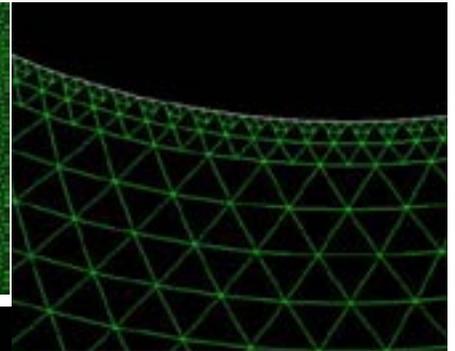
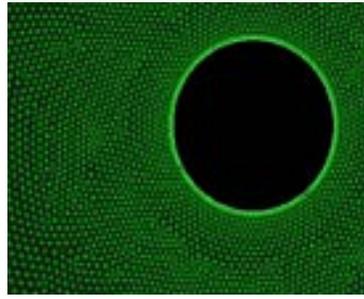
LIFT = -1220.4



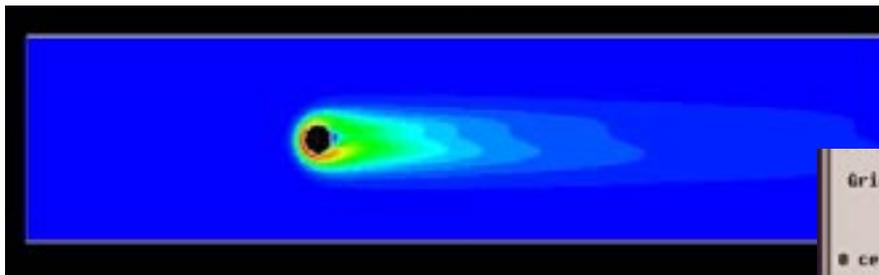
PAGE 8. Next I ran some triangle meshes .Version 1, using a standard Ke model.



Original Gambit Mesh: 100 mesh seeds on circle, 200 bi-exponent on top and bottom walls, 80 front and back walls. 20452 nodes before boundary adaption.



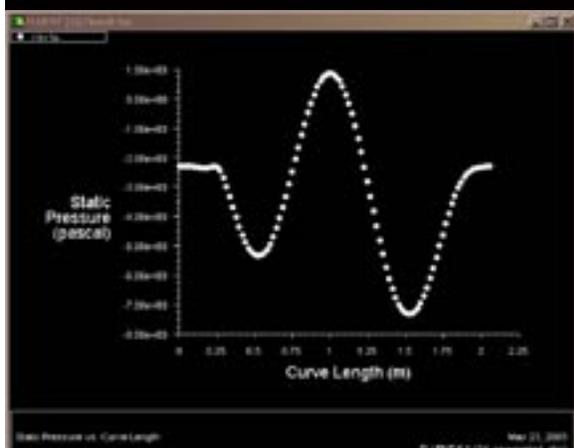
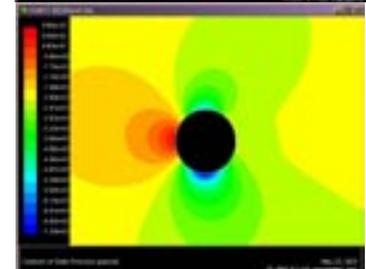
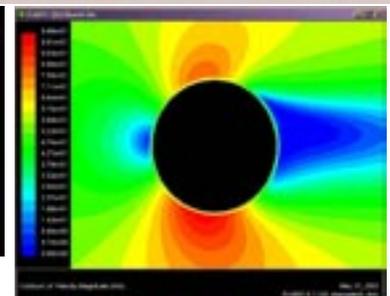
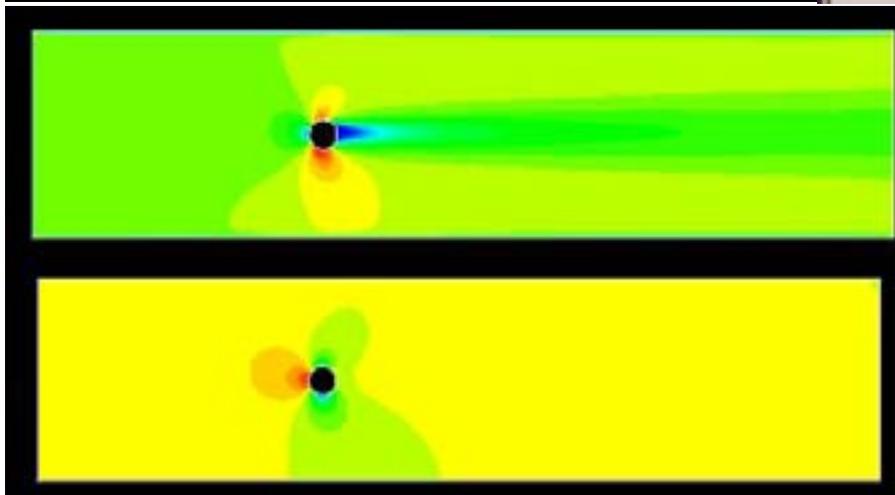
Below: Turbulence, Velocity and Pressure contours.



After Boundary Adaption: 25904 nodes.

Grid size (original / adapted / change)
cells (41732 / 46694 / 4962)
faces (62672 / 72598 / 8926)
nodes (21948 / 25984 / 3964)

0 cells marked for refinement, 8 cells marked for

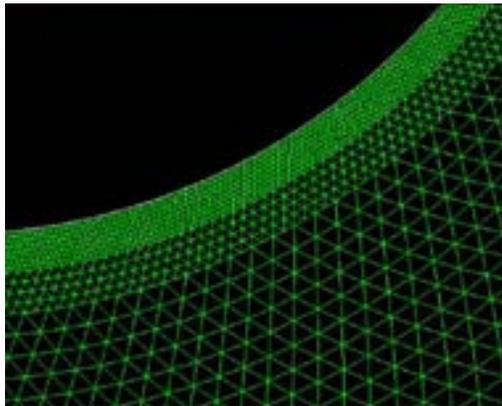
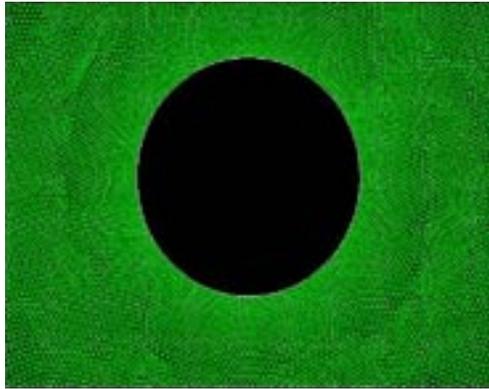


force vector: (0 1 0)				
zone name	pressure force n	viscous force n	total force n	p coeff
sides	958.62018	-1.8239027e-18	958.62018	15
circle	-1012.5214	6.8388889	-1005.6934	-10
net	-53.911194	6.8388889	-47.072305	-88

LIFT = -1005.7

force vector: (1 0 0)				
zone name	pressure force n	viscous force n	total force n	p coeff
sides	0	198.66718	198.66718	15
circle	885.21521	27.118574	913.33378	1
net	885.21521	217.78575	1103.001	1

drag = 913.3

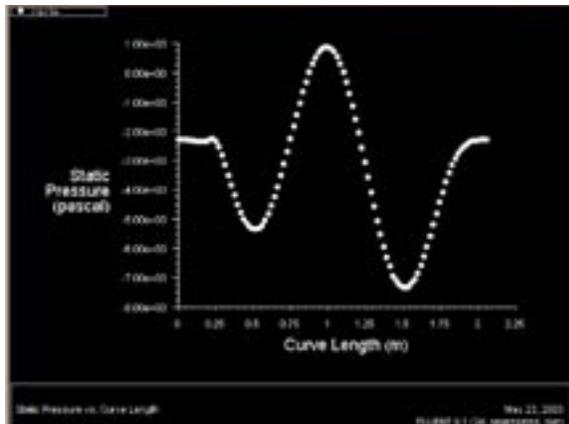
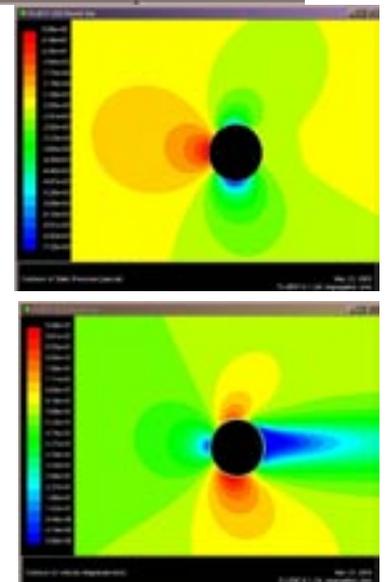
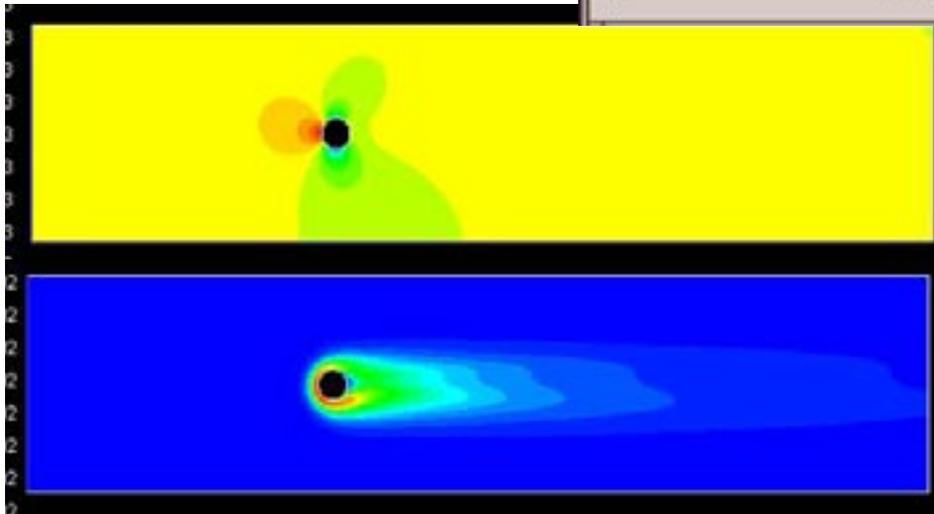


```

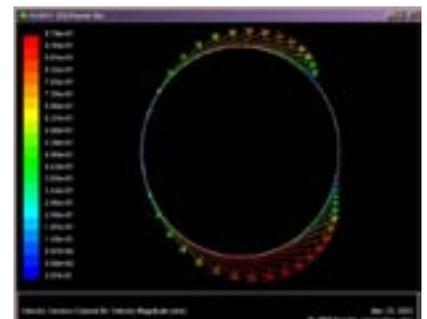
3178 cells marked for refinement, 0 cells marked for coarsening
Dump usage: 85434 cells, 128551 faces, 43117 nodes
Dump usage: 94968 cells, 143645 faces, 48677 nodes
Grid size ( original / adapted / change)
cells ( 85434 / 94968 / 9534)
faces ( 128551 / 143645 / 15094)
nodes ( 43117 / 48677 / 5560)
15838 cells marked for refinement, 0 cells marked for coarsening
Dump usage: 94968 cells, 143645 faces, 48677 nodes
Dump usage: 142482 cells, 216497 faces, 74015 nodes
Grid size ( original / adapted / change)
cells ( 94968 / 142482 / 47514)
faces ( 143645 / 216497 / 72852)
nodes ( 48677 / 74015 / 25338)
    
```

Above: experiment with double boundary adaption.

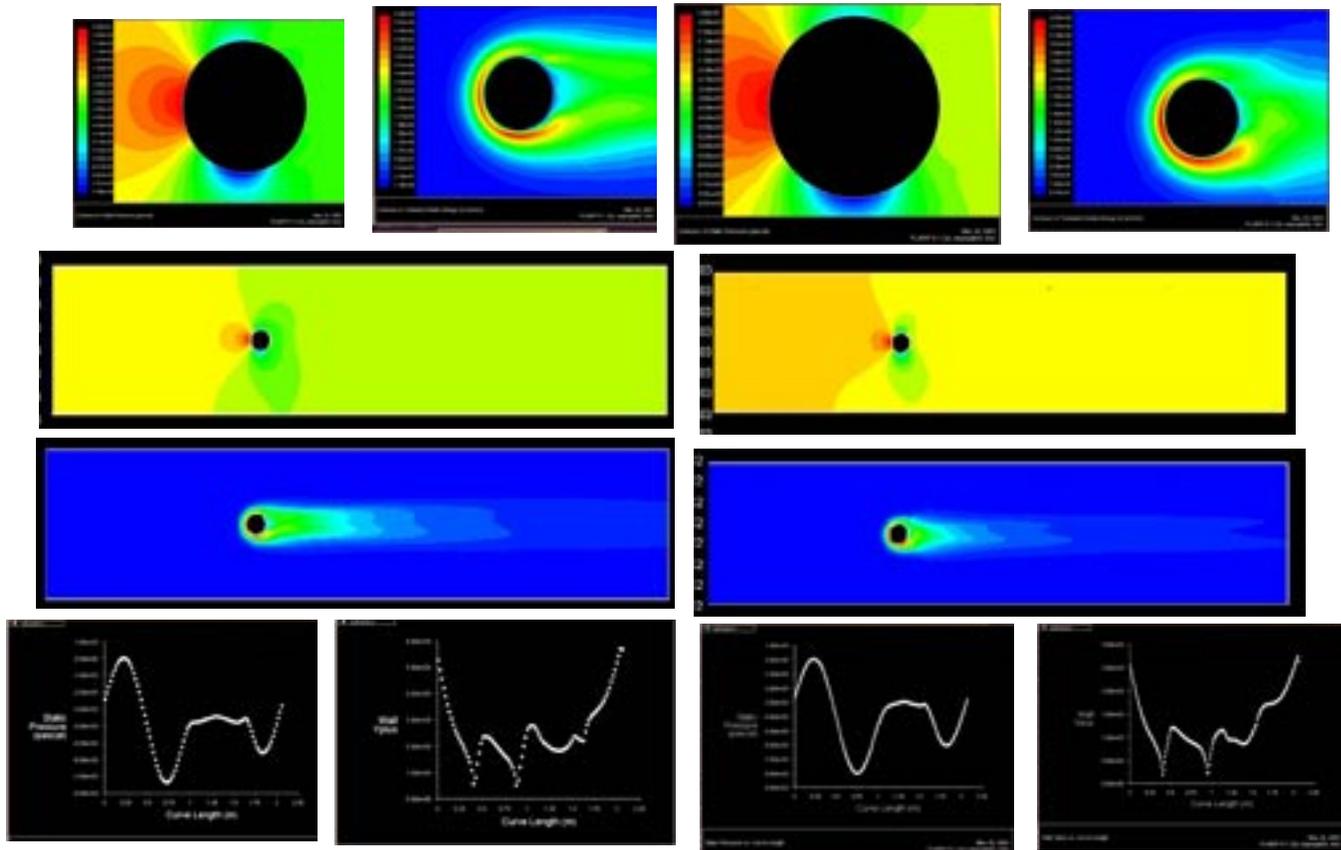
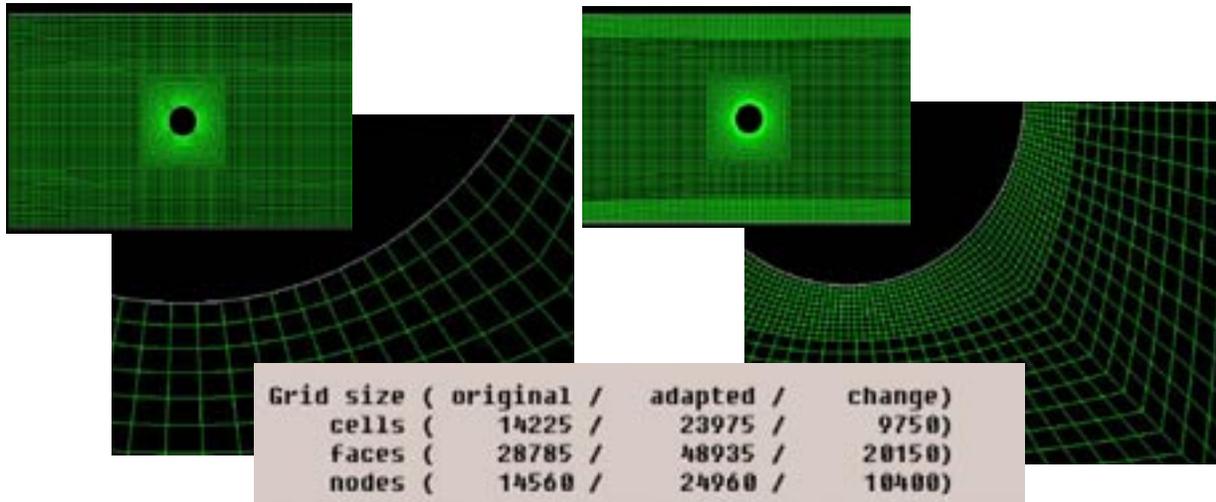
force vector: (0 1 0)			
zone name	pressure force n	viscous force n	total force n
sides	969.57135	-1.803336e-18	969.57135
circle	-1812.4256	6.8439364	-1805.5817
net	-842.854248	6.8439364	-836.010312
force vector: (1 0 0)			
zone name	pressure force n	viscous force n	total force n
sides	0	198.63388	198.63388
circle	886.34174	27.119848	913.46158
net	886.34174	217.75373	1104.0955



Left, above and right: Version 2 Triangular mesh plots and contours. Not much difference in the visuals from the quad mesh, though the lift is less for the equivalent mesh parameters.



PAGE 10. More Experiments with a new Coarse Quad mesh and standard Ke model. Again we see more signs of a novice randomly adapting meshes using the boundary command.



Above: max $y^+ = 6000$

Above max $y^+ = 3000$

zone name	pressure force n	viscous force n	total force n
bottomwall	0	94.518284	94.518284
topwall	0	93.48944	93.48944
wheelac	1886.3222	21.864898	1827.3891
net	1886.3222	286.94562	1215.3878

Force vector: (0 1 0)

zone name	pressure force n	viscous force n	total force n
bottomwall	54574.488	0	54574.488
topwall	53811.884	0	-53811.884
wheelac	778.38743	5.2849298	-705.18269
net	4.982590	5.2849298	-1.4982194

drag= 1027.4

LIFT= -765.2

zone name	pressure force n	viscous force n	total force n
bottomwall	51828.918	0	51828.918
topwall	-50869.852	0	-50869.852
wheelac	-903.89054	4.2881899	-959.68245
net	-4.8241577	4.2881899	-0.61686786

Force vector: (1 0 0)

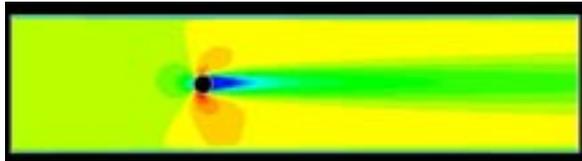
zone name	pressure force n	viscous force n	total force n
bottomwall	0	94.823875	94.823875
topwall	0	93.211266	93.211266
wheelac	864.63922	23.412577	888.0518
net	864.63922	211.44772	1076.0869

Drag= 888.9

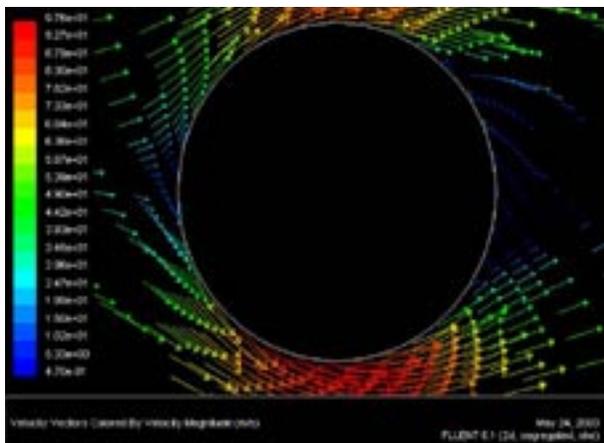
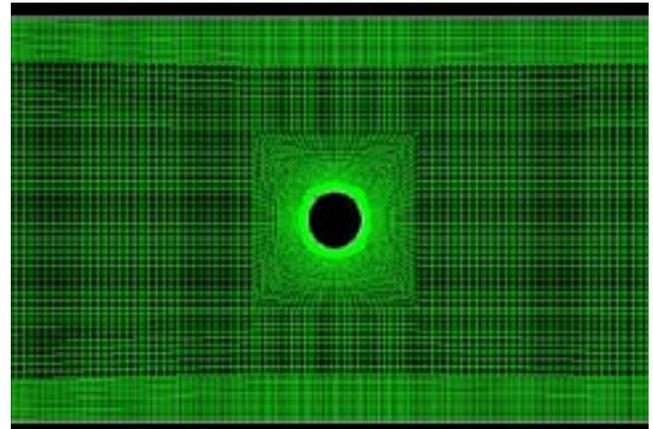
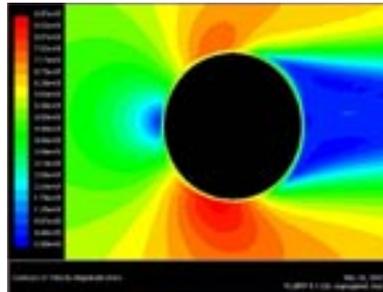
LIFT= -959.68

Later I did the exact same boundary adaption comparison with my final medium quad meshes. Lift went from 1024.7 to 1314.7, maximum y^+ values decreased from 3500 to 1700, and number of nodes increased from 31368 to 33736. The y^+ adaption proved to work better in the end.

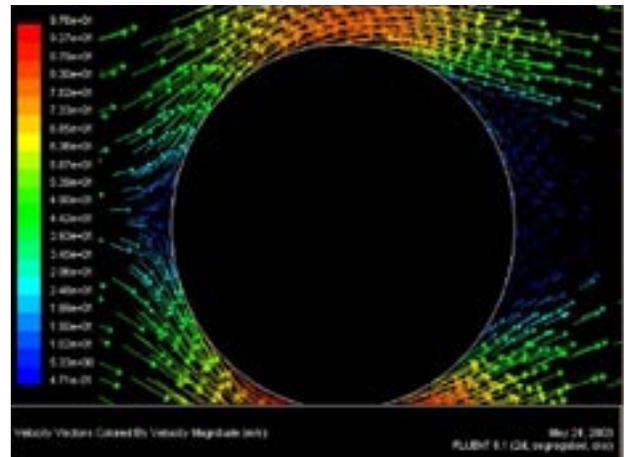
PAGE 11: With the same enhanced coarse quad grid model, I tried the wall function and k omega models and compared results. About this time, I realized that the mesh adaptations were probably adversely affecting my overall results because of the sudden element gradient change that occurs.



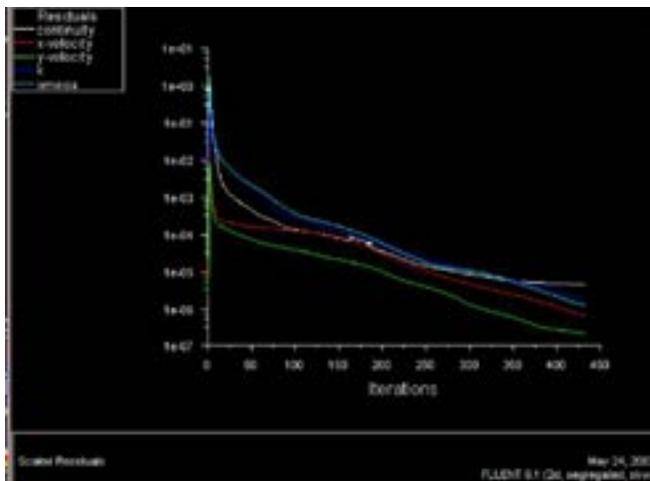
Velocity contours with standard k-e model



Standard K-e model velocity vectors



Enhanced Wall Function velocity vectors. Below: forces from K-e model with enhanced wall function.



zone name	pressure force n	viscous force n	total force n
bottomwall	0	95.198813	95.198813
topwall	0	93.575264	93.575264
wheeloc	865.16516	23.486465	888.65163
net	865.16516	212.25974	1077.4249

Force vector: (8 1 8)

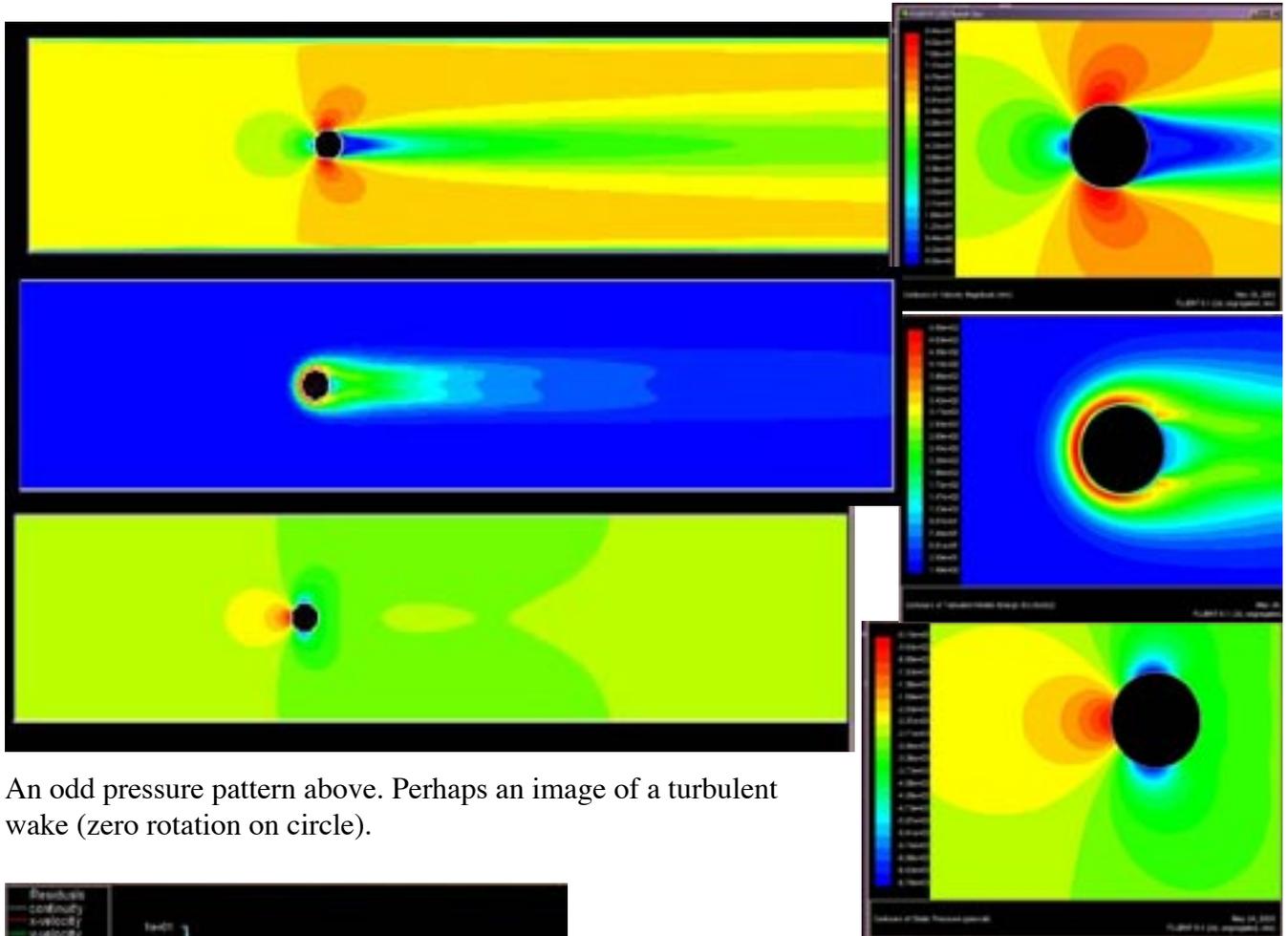
zone name	pressure force n	viscous force n	total force n
bottomwall	51822.324	0	51822.324
topwall	-50668.852	0	-50668.852
wheeloc	-968.2785	4.285663	-964.0728
net	-4.882472	4.285663	-0.600809

Force vector: (8 1 8)

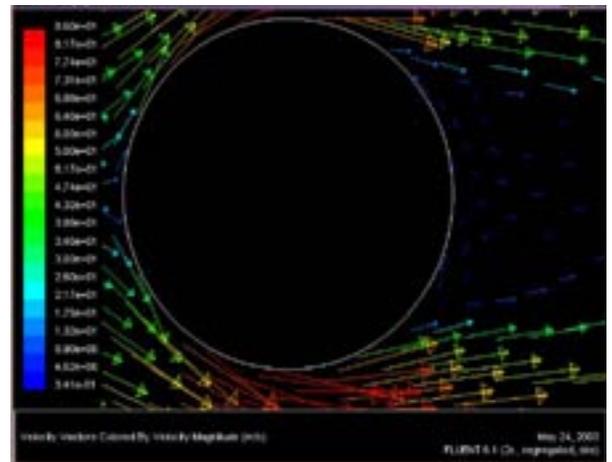
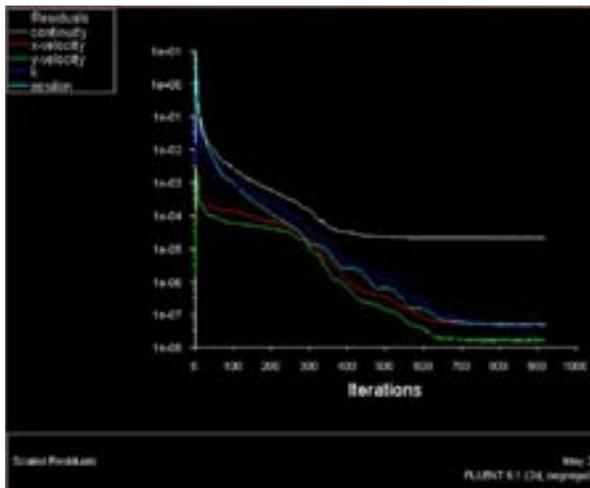
zone name	pressure force n	viscous force n	total force n
bottomwall	62932.152	0	62932.152
topwall	-62195.457	0	-62195.457
wheeloc	-745.83337	7.1379066	-738.69547
net	-9.1388615	7.1379066	-2.000155

Left: Iteration plot and K Omega results with boundary adapted coarse quad grid.

Page 12: For reference, another run with zero rotation on the circle. This is with the original medium quad mesh, using standard K-e second order solution.



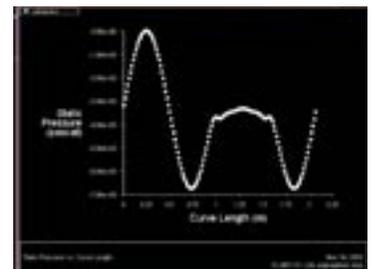
An odd pressure pattern above. Perhaps an image of a turbulent wake (zero rotation on circle).



zone name	pressure force	viscous force	total force
	x	y	
bottomwall	54444.164	9.5576806e-10	54444.164
topwall	-54444.16	-9.5580761e-10	-54444.16
wheelac	8.8811280889	-2.477318e-07	8.8811280711
net	8.8858272089	-2.477318e-07	8.8858289911

zone name	pressure force	viscous force	total force
	x	y	
bottomwall	54444.164	9.5576806e-10	54444.164
topwall	-54444.16	-9.5580761e-10	-54444.16
wheelac	8.8811280889	-2.477318e-07	8.8811280711
net	8.8858272089	-2.477318e-07	8.8858289911

LIFT= zero



Max $y^+ = 3000$

PAGE 13: Here's something interesting. I used a boundary adapted medium quad mesh for the first example, then a non-adapted grid for the second. The differences using a Reynold's Stress model were significant.

Viscous Model

Model

- Inviscid
- Laminar
- Spalart-Allmaras (1 eqn)
- k-epsilon (2 eqn)
- k-omega (2 eqn)
- Reynolds Stress (5 eqn)

Reynolds-Stress Options

- Wall B.C. from k Equation
- Quadratic Pressure-Strain Model
- Wall Reflection Effects

Near-Wall Treatment

- Standard Wall Functions
- Non-Equilibrium Wall Functions
- Enhanced Wall Treatment

Model Constants

Cmu: 0.09

C1-Epsilon: 1.44

C2-Epsilon: 1.92

C1-PS: 1.8

```

Reading "C:\FLOENT\INC\atbin\atx86\Whee112ae
31368 nodes.
  968 mixed interior faces, zone 3.
  345 mixed wall faces, zone 4.
  345 mixed wall faces, zone 5.
  81 mixed velocity-inlet faces, zone 6.
  81 mixed outflow faces, zone 7.
  148 mixed wall faces, zone 8.
  48268 mixed interior faces, zone 10.
  38868 quadrilateral cells, zone 2.
    
```

Same model for both runs below.

Velocity Inlet

Zone Name: Inlet

Velocity Specification Method: Magnitude, Normal to Boundary

Reference Frame: Absolute

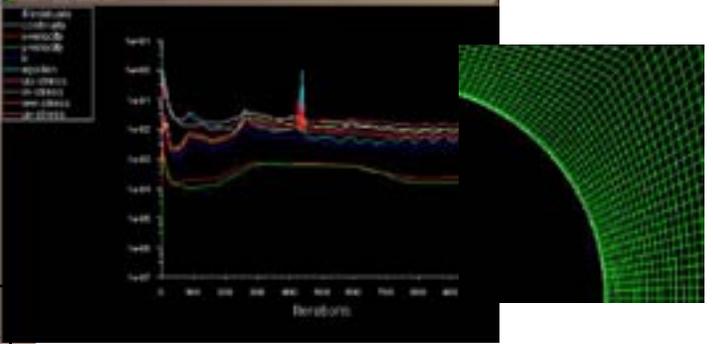
Velocity Magnitude (m/s): 55.6 constant

Turbulence Specification Method: Intensity and Length Scale

Turbulence Intensity (%): 1.4839

Turbulence Length Scale (m): 0.52765

slightly different Turbulent Intensity.

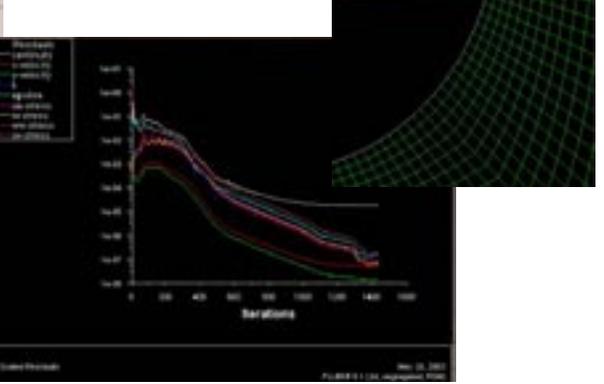


Above run with boundary adapted mesh.. Below with unadapted mesh and correct turbulence boundary conditions.

Force vector: (0 1 0)

zone name	pressure force n	viscous force n	total force n
bottomwall	35615.482	0	35615.482
topwall	-32175.15	0	-32175.15
wheel0	-3321.1689	1.6543653	-3319.5146
net	119.88381	1.6543653	128.73737

LIFT = -3319.5



Velocity Inlet

Zone Name: Inlet

Velocity Specification Method: Magnitude, Normal to Boundary

Reference Frame: Absolute

Velocity Magnitude (m/s): 55.6 constant

Turbulence Specification Method: Intensity and Length Scale

Turbulence Intensity (%): 1.82

Turbulence Length Scale (m): 0.52765

iter continuity x-velocity y-velocity k epsilon nu-stress

1425 1.785e-05 4.928e-08 1.4154e-08 3.1336e-08 1.988e-07 8.5757e-08

1426 1.7718e-05 4.8933e-08 1.4213e-08 3.1337e-08 1.9642e-07 8.9889e-08

iter continuity x-velocity y-velocity k epsilon nu-stress

1425 1.785e-05 4.928e-08 1.4154e-08 3.1336e-08 1.988e-07 8.5757e-08

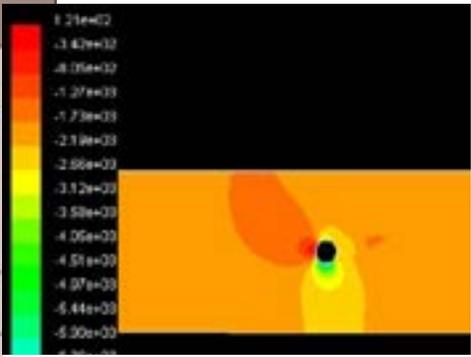
1426 1.7718e-05 4.8933e-08 1.4213e-08 3.1337e-08 1.9642e-07 8.9889e-08

Force vector: (0 1 0)

zone name	pressure force n	viscous force n	total force n
bottomwall	39417.185	3.4889150e-18	39417.185
topwall	-37382.996	-1.9805494e-18	-37382.996
wheel0	-2817.852	8.9533828e-18	-2816.892
net	7.857273	8.9533828e-18	8.9186719

LIFT = -2016.1

Turbulent Intensity.



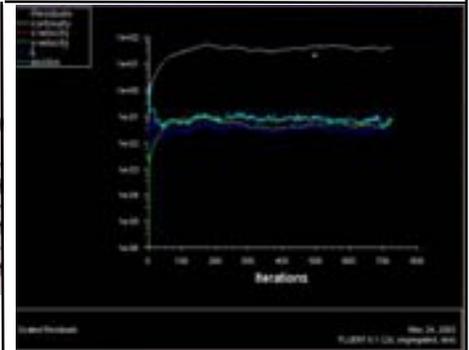
From this it became clear how sensitive some models were to initial conditions and mesh parameters. Left: an interesting bubble behind the cylinder in the pressure contour from this run.

PAGE 14: At this point I redid all my meshes and ended up with semi-final versions which were much more consistent in terms of grid size (more square around circle), and pattern in the adjoining faces (see main results). With these meshes, I performed more iterations.

```

353 solution is converged
353 9.6237e-06 2.3588e-06 1.0107e-06 9.7818e-06 5.1980e-06 0:36:24 4986

Force vector: (0 1 0)
zone name      pressure force      viscous force      total force
              n              n              n
-----
bottomwall     LIFT =          53025.379  1.1122354e-18  53025.379
topwall       -740.4         -52281.781 -6.6042912e-19 -52281.781
wheeloc       -744.79285    4.3657598  -748.42709
net           -1.1951904    4.3657598  3.1705694
    
```



Results of runs with unadapted final quad meshes w/ first order SIMPLE discretiation. Above: Run with medium mesh. Below: First order SIMPLE run with fine mesh.

```

471 1.8235e-05 8.8816e-06 3.2591e-06 2.1235e-05 9.5898e-06 0:40:48 455

Interrupting...
Done.

Force vector: (0 1 0)
zone name      pressure force      viscous force      total force
              n              n              n
-----
bottomwall     LIFT =          53211.781  1.5648476e-18  53211.781
topwall       -949.1         -52237.402 -1.2511805e-18 -52237.402
wheeloc       -953.84381    4.677834  -949.16598
net           20.535095     4.677834  25.212929
    
```

Above: Another botched attempt using the PISO discretiation. I'm not sure what went wrong here. PISO is recommended for transient flow calculations with a large time step, so that could be the problem (although I did not check the under relaxation factors, which I assumed would be set a recommended default level).

inlet

Velocity Specification Method: Magnitude, Normal to Boundary

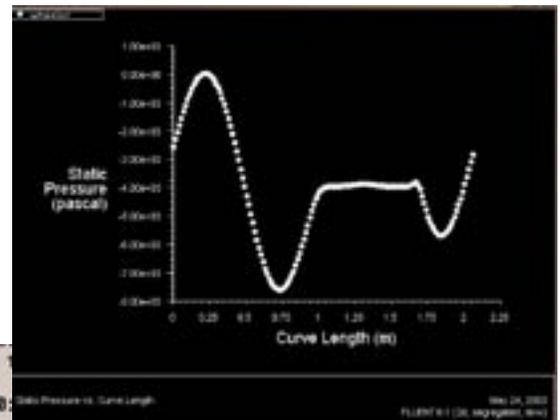
Reference Frame: Absolute

Velocity Magnitude [m/s]: 55.6 constant

Turbulence Specification Method: K and Omega

Turb. Kinetic Energy [m2/s2]: 1.536 constant

Spec. Dissipation Rate [1/s]: 0.592 constant



```

turbulent viscosity limited to viscosity ratio of 1.000000e+05 in 1
395 solution is converged
395 9.9972e-06 6.2345e-07 3.1907e-07 1.8117e-06 1.5386e-06 0:00:00

Force vector: (0 1 0)
zone name      pressure force      viscous force      total force
              n              n              n
-----
bottomwall     LIFT =          61785.387  5.9107002e-19  61785.387
topwall       -80934.609    4.8090132e-20 -80934.609
wheeloc       -863.43370    0.189405  -855.24424
    
```

Left and above: Results from using a standard (left) and SST (left and (bottom left) k-omega models. Note the message (which seems to be dependent on initial boundary <inlet> conditions) “turbulent viscosity limited to a viscosity ratio of...” in both results, something which I made sure to avoid in my other models. The number of cells this occurred in decreased in the SST model. The K-omega is a low Reynold’s number model in any case.

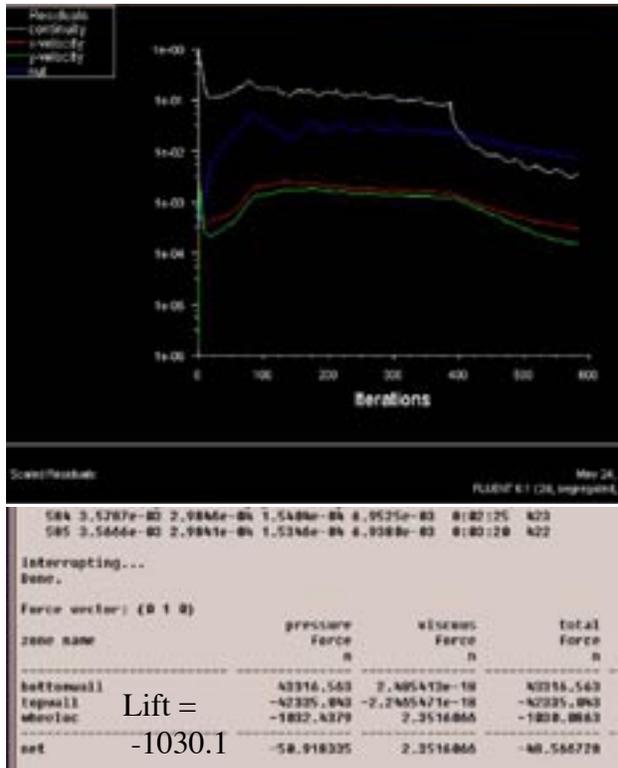
```

turbulent viscosity limited to viscosity ratio of 1.000000e+05 in 6312 c
245 9.2200e-03 1.8586e-04 1.7678e-04 8.3588e-04 4.8434e-04 0:03:08 2

Interrupting...
turbulent viscosity limited to viscosity ratio of 1.000000e+05 in 6326 c
Done.

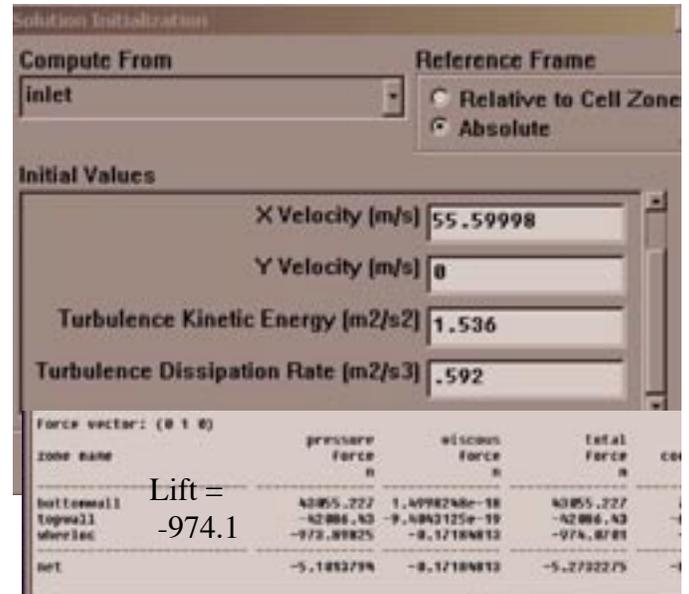
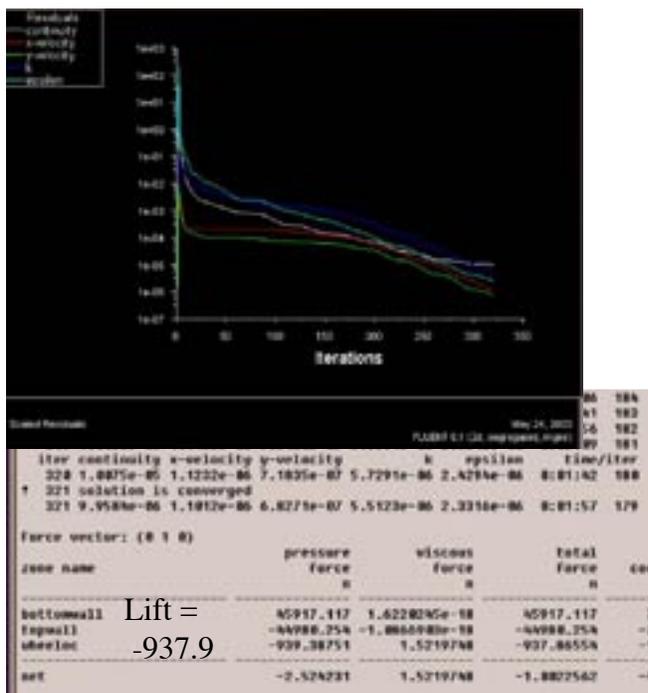
Force vector: (0 1 0)
zone name      pressure force      viscous force      total force
              n              n              n
-----
bottomwall     LIFT =          52617.891  1.2481485e-18  52617.891
topwall       -51402.652    -3.3523415e-19 -51402.652
wheeloc       -1064.656     6.6009502  -1058.0551
net           158.58228     6.6009502  157.18223
    
```

PAGE 15: More runs, this time with various turbulence models. Again all runs were with the final quad medium coarse mesh (31368 nodes, no adaption). These runs compare to the lift from the Standard K-E model at -1024.8.

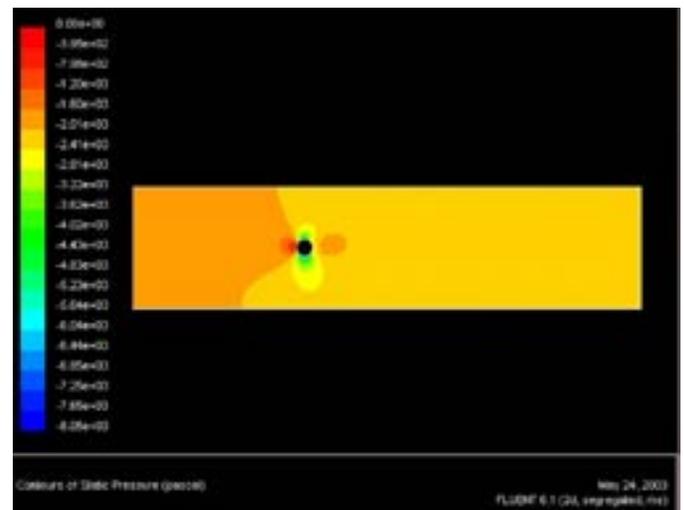


Above: Spalart Allmaras model run. The sudden drop in continuity after a certain number of iterations was from a change in under relaxation factors. The model ran quickly but residuals did not drop below 0.001

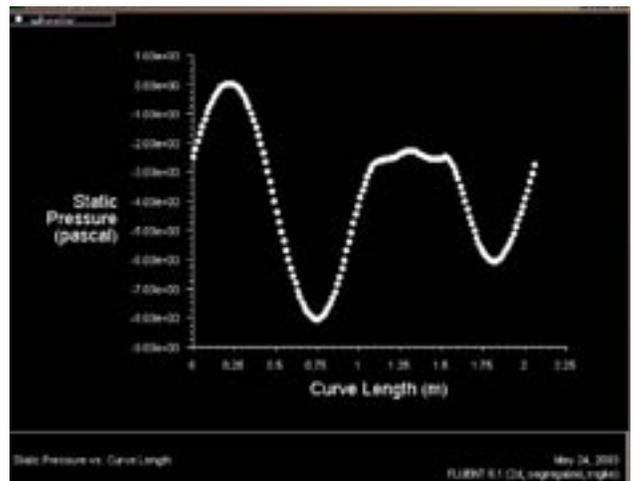
Below: K-e RNG model run. Converged to 0.0001 residual level after 321 iterations.



Right side of page: K-e Realizable Model with reworked turbulent dissipation rate plugged in. It converged to 0.0001 residual level after 335 iterations.



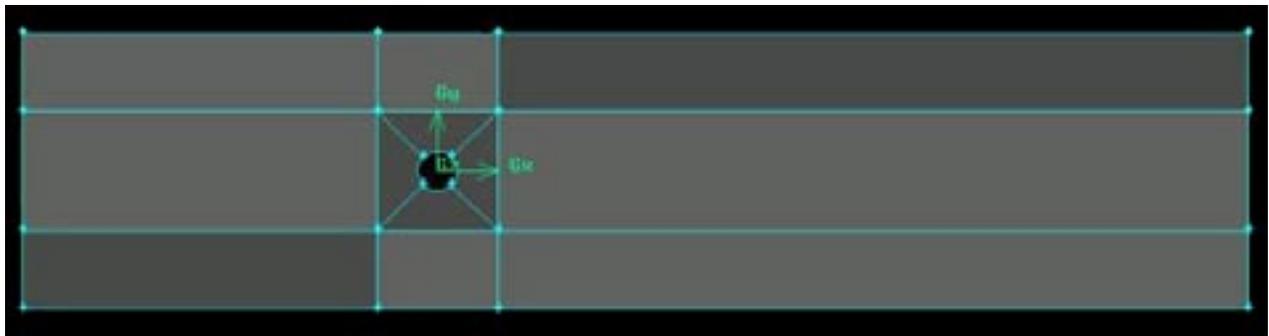
Above: another interesting pressure bubble (K-e Realizable solution).



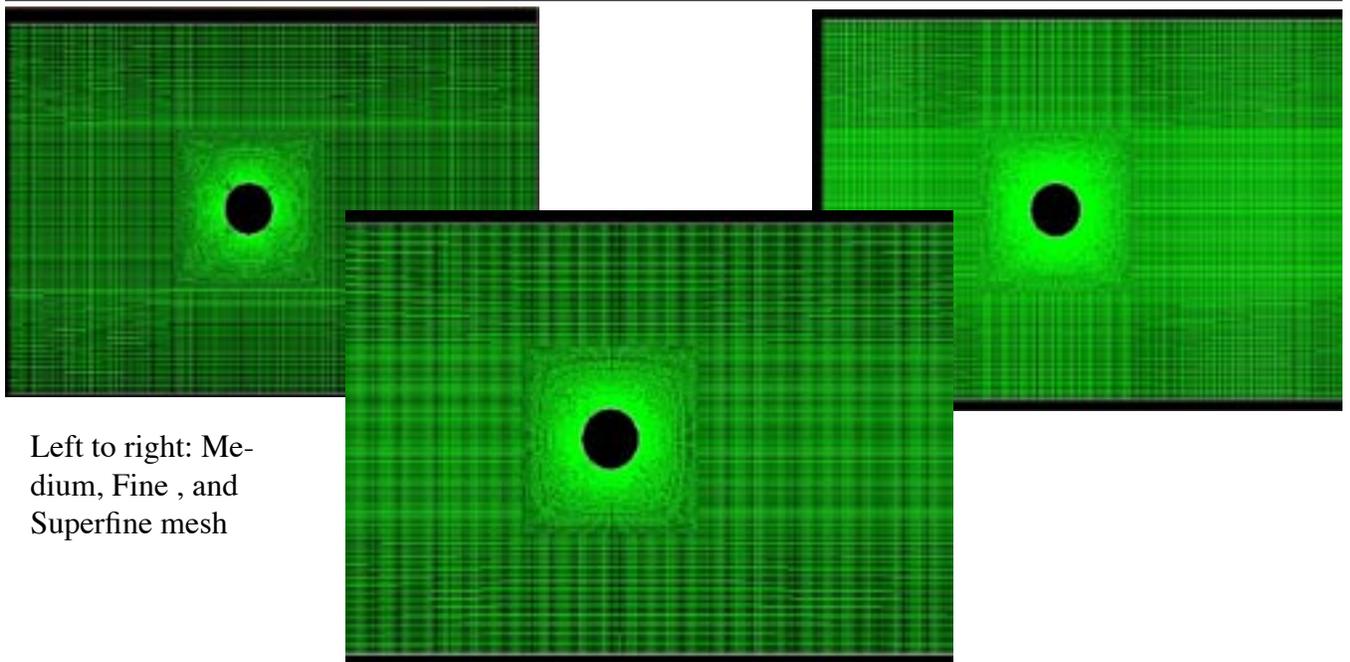
PAGE 16: At this point, thinking that I was on the right track, I ran a complete set of tests on “new improved” versions the medium, fine, and superfine quad meshes (12 faces). I focused on keeping the grid shape square with less than 5% gradient change from cell to cell. Initially all these runs showed high y^+ values, but after a series of adaptations and iterations I was able to bring the y^+ values down to the 350 range, which I believed acceptable for this higher Reynold’s number flow.

These tests were rerun with a standard K-epsilon model with standard wall functions, second order SimpleC discretiation with standard pressure discretiation. The inlet turbulent boundary conditions were initialized with the intensity and length scale values based on a hydraulic diameter of 0.411 (which assumed a unit width of one, inlet 4.62m high). Length scale calculated as $l=0.07$ (hydraulic diameter, and intensity using the formula of $I = 0.16(Re_{Dh})^{-1/8}$.

The following pages contain the results. These were all based on the following meshes, consistent in their scale:



Mesh Seeds:	Circle	Inner radials	Int. horizontals	Int. verticals	Total Nodes
Medium	148	0.05 /1.05	0.06	0.06 / 1.05	31368
Fine	240	0.0375/1.05	0.0375	0.05 / 1.05	47095
SuperFine	300	0.025/1.05	0.03	0.04 / 1.05	97096
(units)	Number of	Size/Suc.Ratio	SIze	Size/ratio	

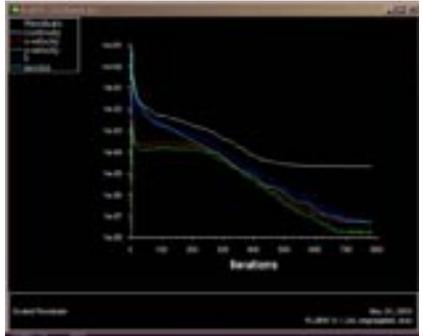
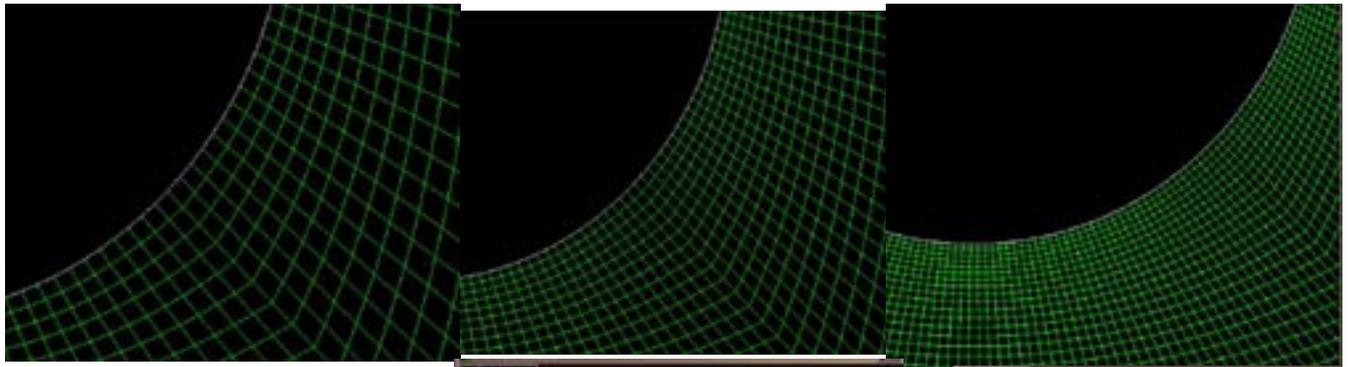


Left to right: Medium, Fine, and Superfine mesh

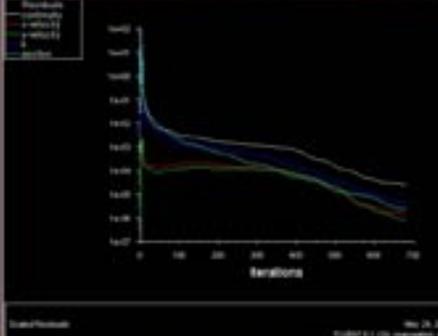
Medium Mesh Results

Fine Mesh Results

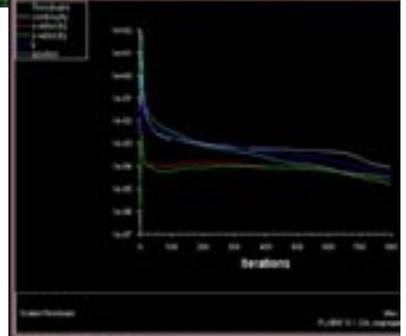
“SuperFine” Mesh Results



Lift = -1024.7
Drag = 960.1



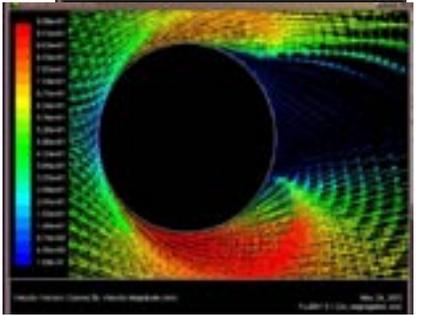
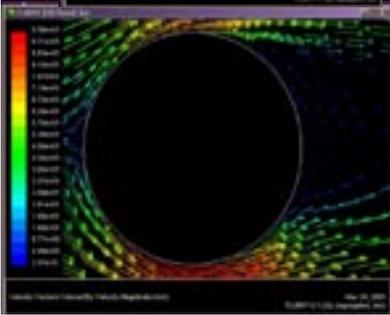
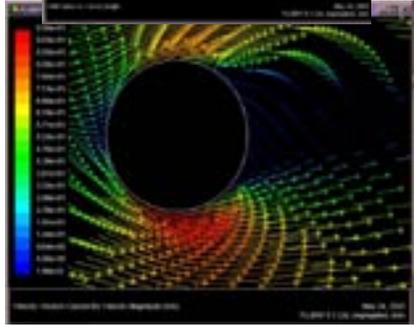
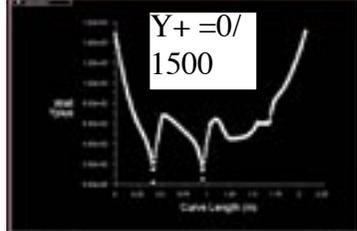
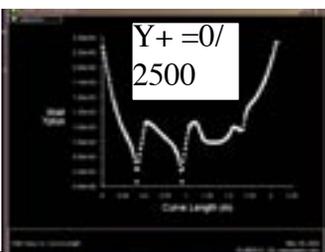
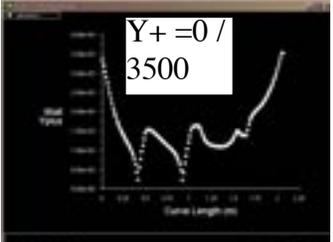
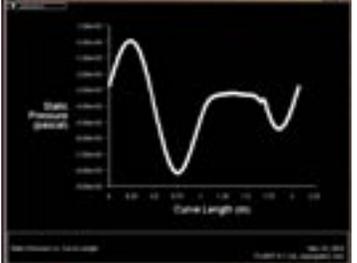
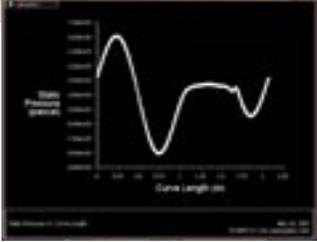
Lift = -1179.2
Drag = 930.2

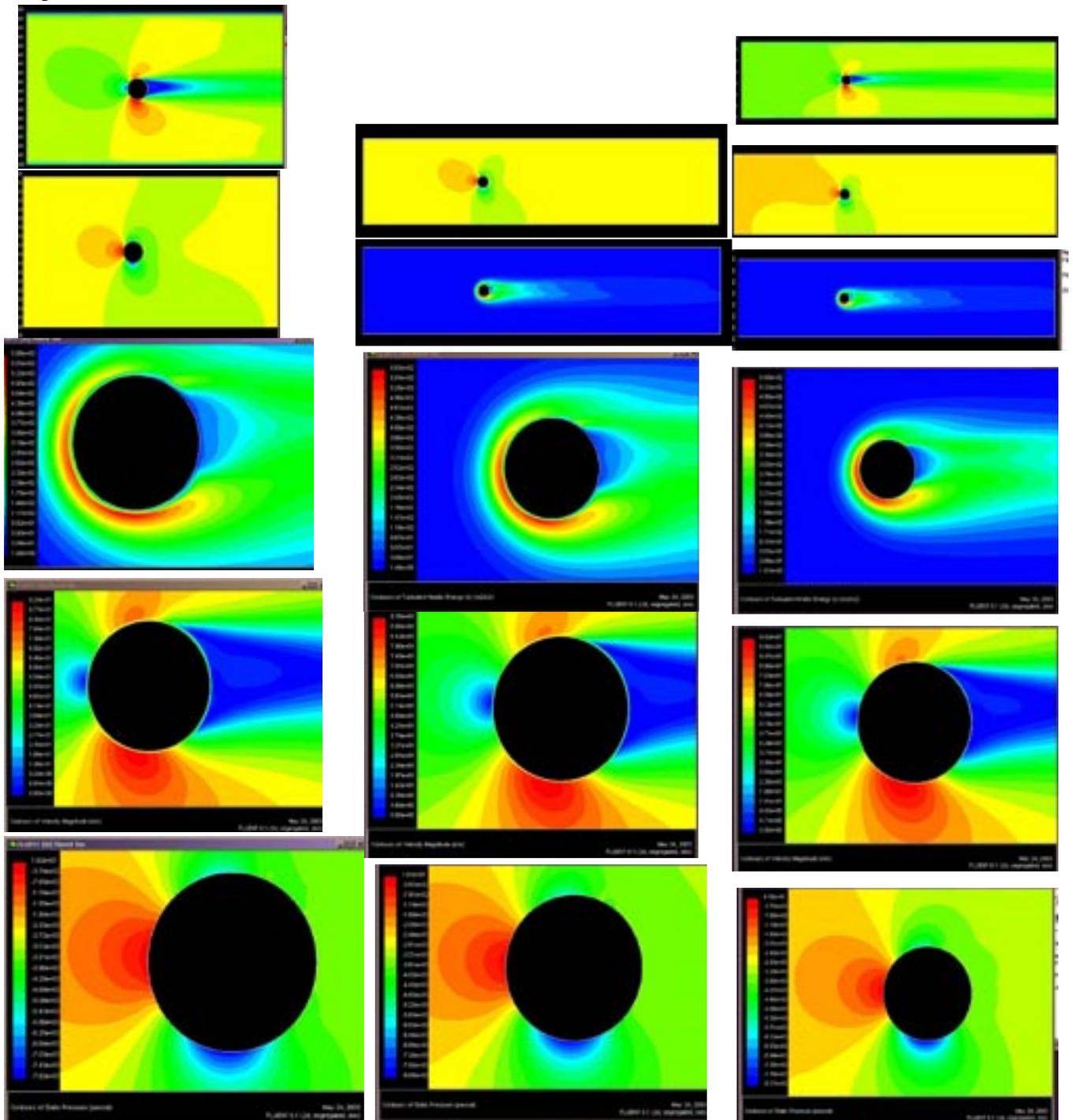


Lift = -1278.5
Drag = 908.0

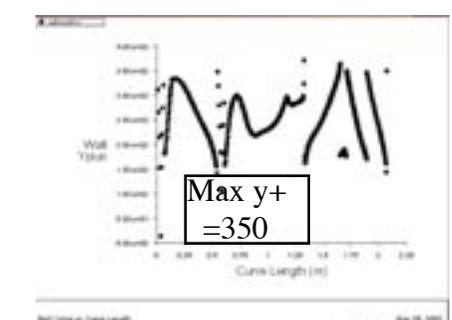
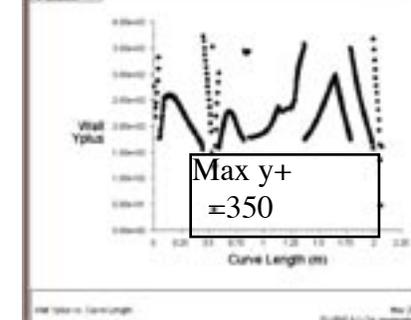
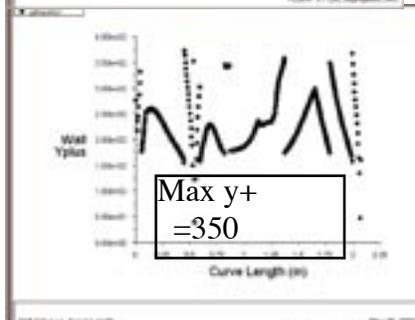
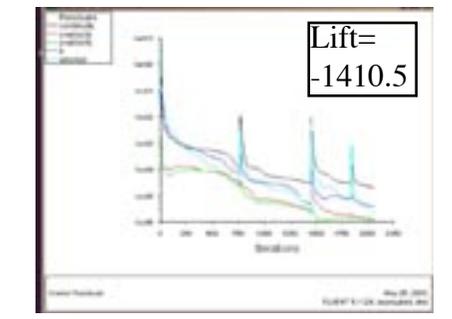
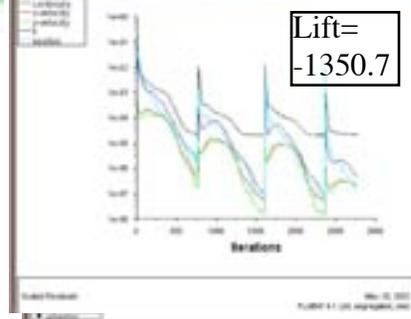
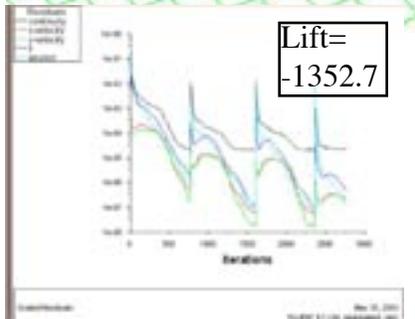
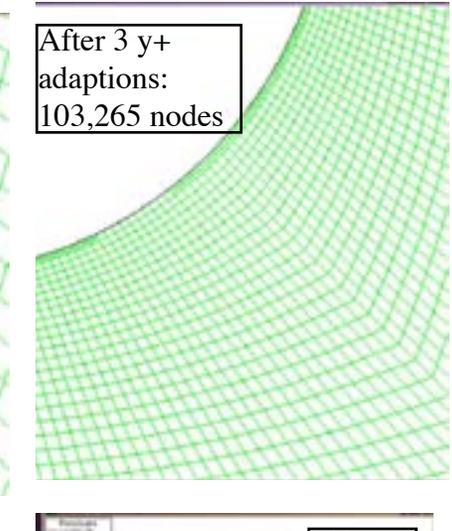
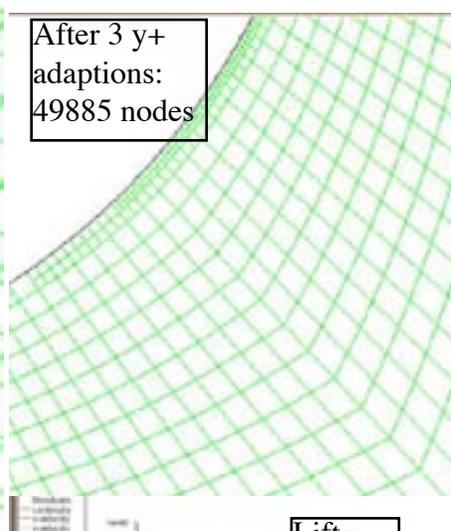
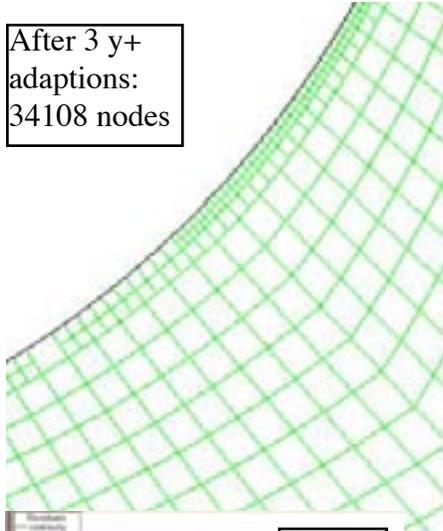


Zero pressure line normal

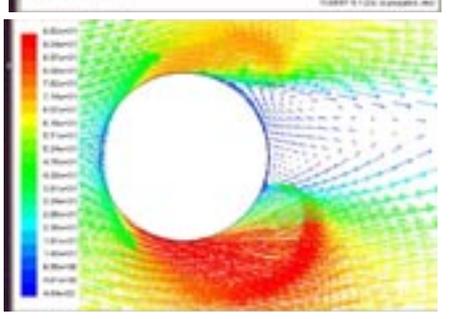
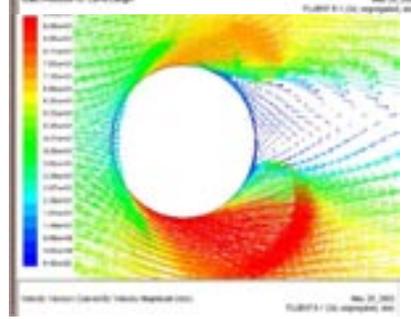
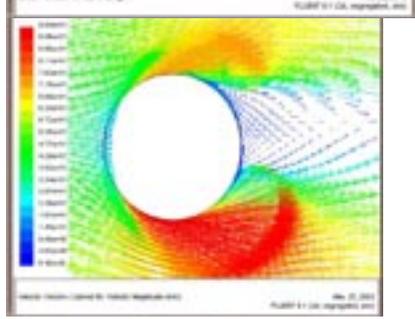
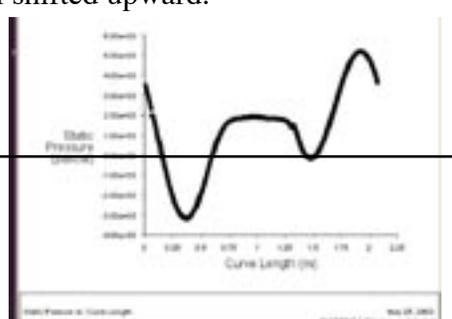
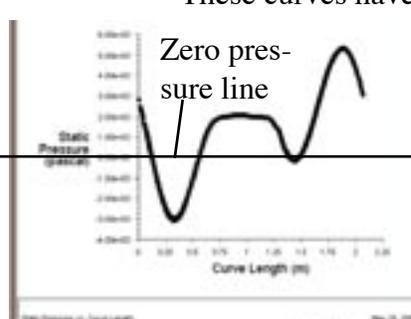
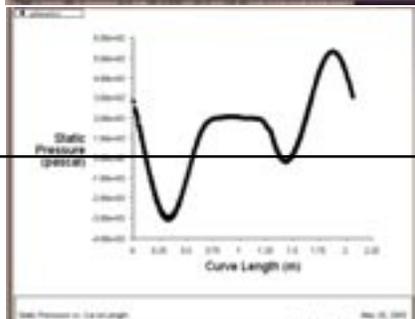


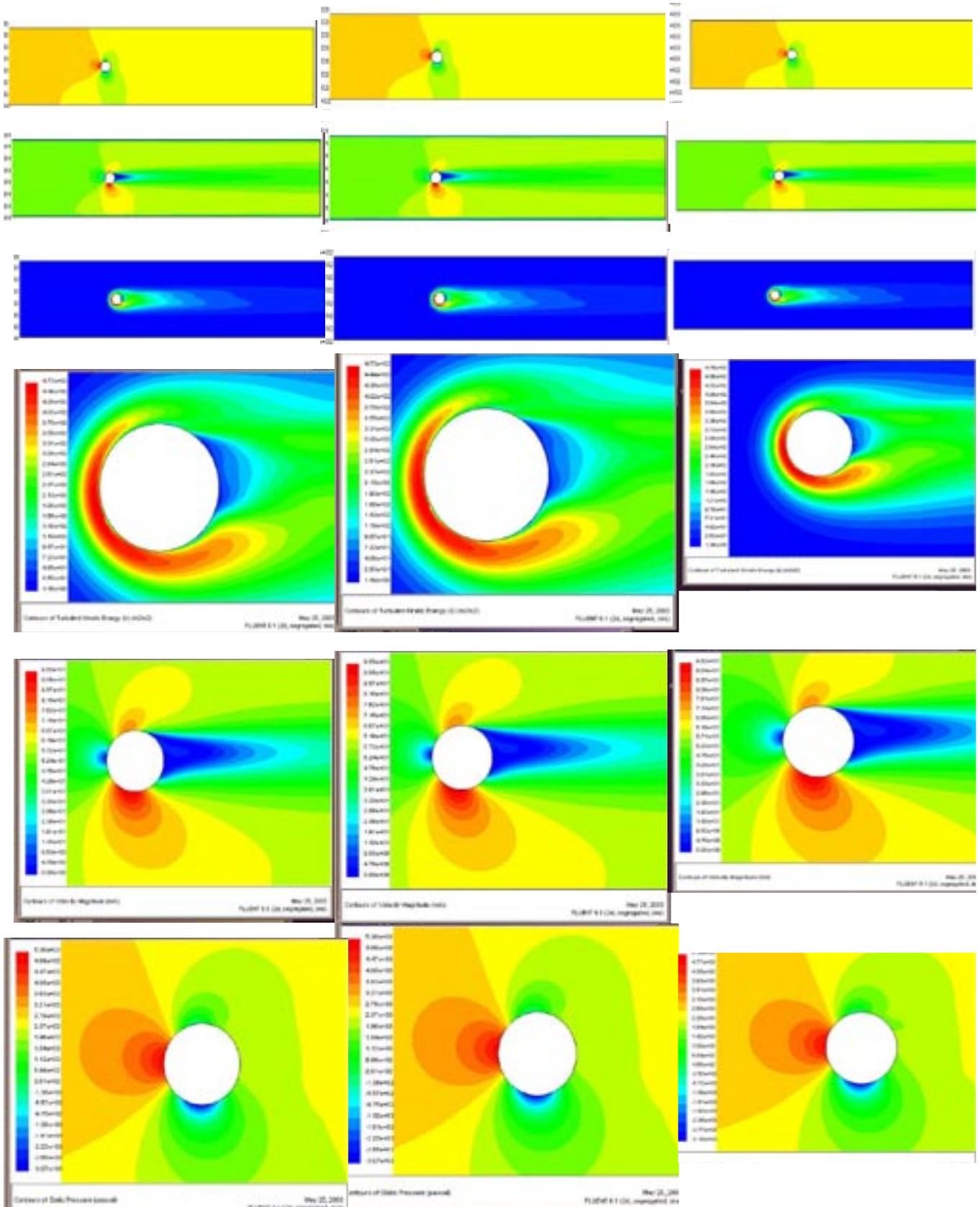


Comment and Observations: Even for the “superfine” mesh, initial y^+ values are too high. This should have prompted me to create a finer mesh around the circle, but I was thinking at the time that doing so would exceed 100,000 nodes, since I was under the understanding that mesh size needed to be rectangular, and that the gradient could never exceed 5% (discussion with John Reizes, May 2003). Now I realize that more nodes in the boundary zones of interest is much more important for an accurate result, and perhaps a 8% increase in grid from cell to cell may be preferable. Another thing that becomes clear while comparing this data side by side is that the contours don’t change much for a given viscous turbulence model, but the functionals do. I focused primarily on the lift coefficients, but now I realize that there is a pattern to the converging solution, namely, that lift increases, and drag decreases. Therefore, I should look in the future at the lift/drag ratios. This basic observation only came to me later, however, and I next went though an obsessive and probably useless adaption process.



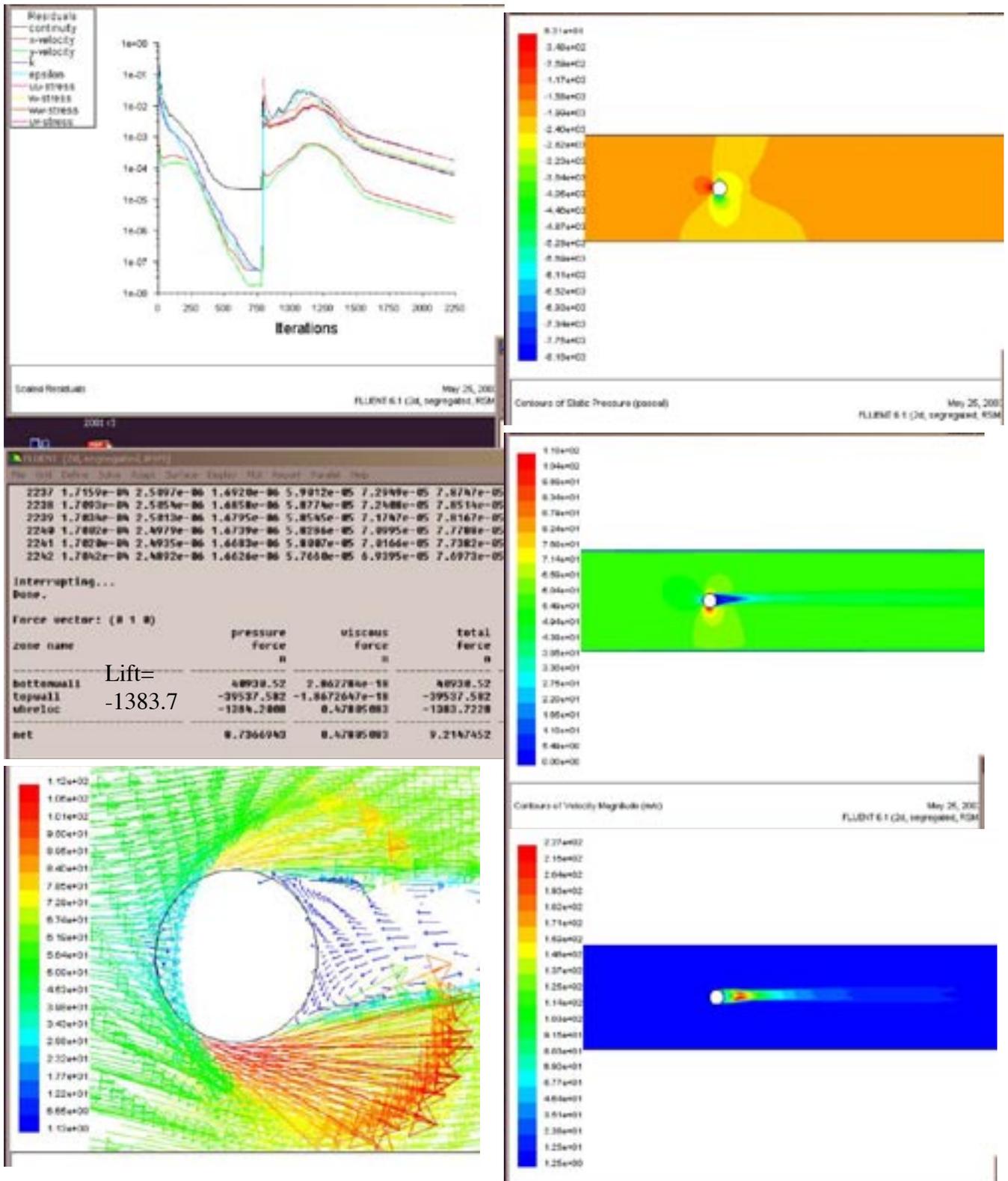
These curves have all shifted upward.





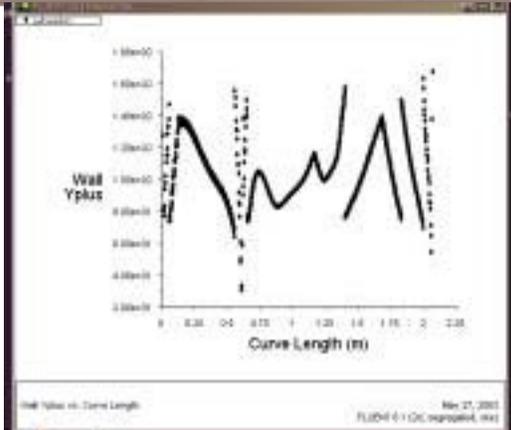
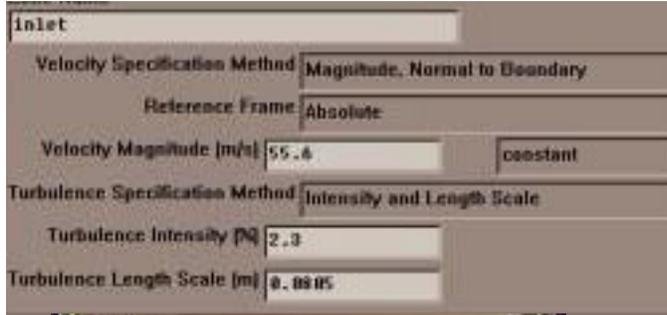
Observations: Consistent and similar results, yet still probably with a lot of error. Looking at the meshes one can see frequent gradients, probably not a good thing. Unfortunately, I neglected to record the drag values for these runs. But at least I at last learned how to plot white backgrounds.

Page 21. Reynold's Stress Model again, this time with the medium mesh (unadapted) after it had already been solved by the Ke standard turbulence model.

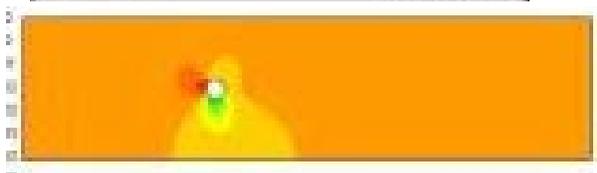
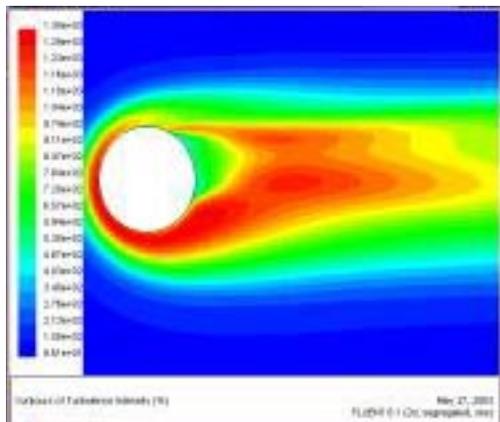


Observations: The results are quite similar to the Ke model solution, yet the contours look underdeveloped and may represent an unconverged solution.

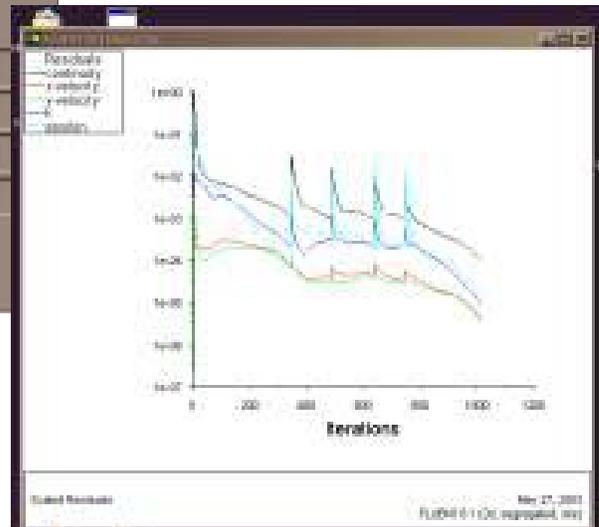
PAGE 22: The next couple runs involve changing two parameters. The main one the use of the PRESTO pressure discretiation scheme. The other is a change to the inlet turbulence setting. Using PRESTO, I was getting the message regarding turbulence viscosity level limit in x number of cells, so I reworked the turbulence parameters based on a Hydraulic diameter of 0.411, which assumes a 4.62 meter square inlet condition, which resulted in a length scale of $0.07 \cdot 0.411 = 0.0805$, and an Intensity of 2.3%, using the standard formula as before. Below Fine mesh results.



Y+ values dropped from 1200 maximum after the first run to 175 after several y+ adaption runs. The fact that the curve breaks up like this is a bit troubling, but the y+ values began smaller, and got smaller faster, using PRESTO.



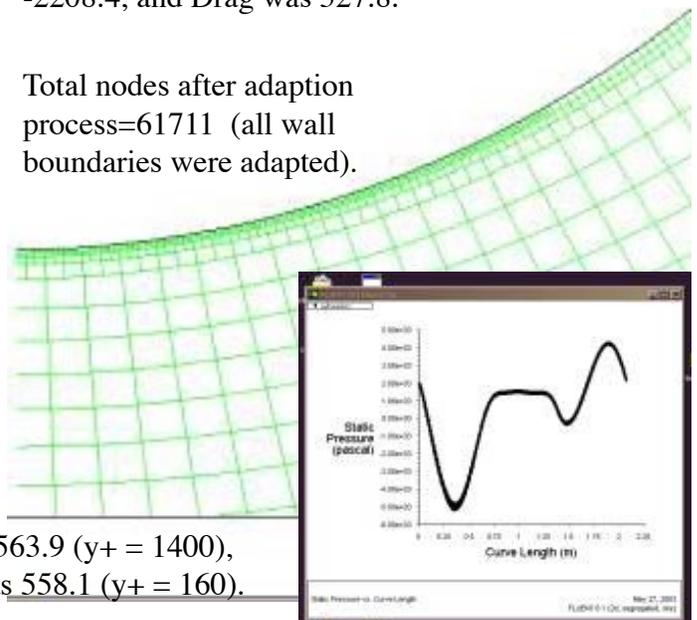
Similar results occurred for the Superfine Mesh. Initial run indicated a lift and drag of -2182.0 and 563.9 ($y+ = 1400$), and after 4 adaptions, lift was -2161.9 and drag was 558.1 ($y+ = 160$).



area name	pressure force	viscous force	total force
bottomwall	0	95.253717	95.253717
topwall	0	92.466081	92.466081
inlet	532.297778	19.244660	551.542438
out	-532.297778	-19.244660	-551.542438
Force vector = (0 1 0)			
area name	pressure force	viscous force	total force
bottomwall	-0.000000	0.000000e+00	-0.000000
topwall	0.000000e+00	0.000000e+00	0.000000
inlet	-17.2268118	0.50050208	-17.7273139

Note: after first run with PRESTO, Lift was -2208.4, and Drag was 527.8.

Total nodes after adaption process=61711 (all wall boundaries were adapted).



PAGE 23: The previous results were mostly done in a flurry of activity using the manuals to help decipher the complex program, and are mostly worthless results. However, after writing all the previous pages up I was able to take a calm look at the results thus far, and a few important things suddenly dawned. The basic principles of fluid dynamics were at last considered. In the previous tests, I had chosen mostly to look at lift as my functional, and I hoped to get a consistent, converging lift result. But as you can see, values change dramatically depending on the turbulence model. It's clear that even my finest grid was not fine enough in then area of interest. Most importantly, I realized that a random blunt approach does not work for the complex study of turbulent fluid dynamics, and that before any study it is important to consider carefully the underlying principles. The relationship between lift and drag in the CFD solutions seemed consistent: as Fluent results showed increased lift, the drag values would decrease). Perusing some established research, I uncovered the diagram below. I also used this time to write up my report, and in the ensuing wrestling with the Fluent manual, I discovered that it is possible to look at the forces (lift and drag) in a plotted version as the model solves. This was a key to the next step of understanding.

Sailing With a Rotating Cylinder Sail

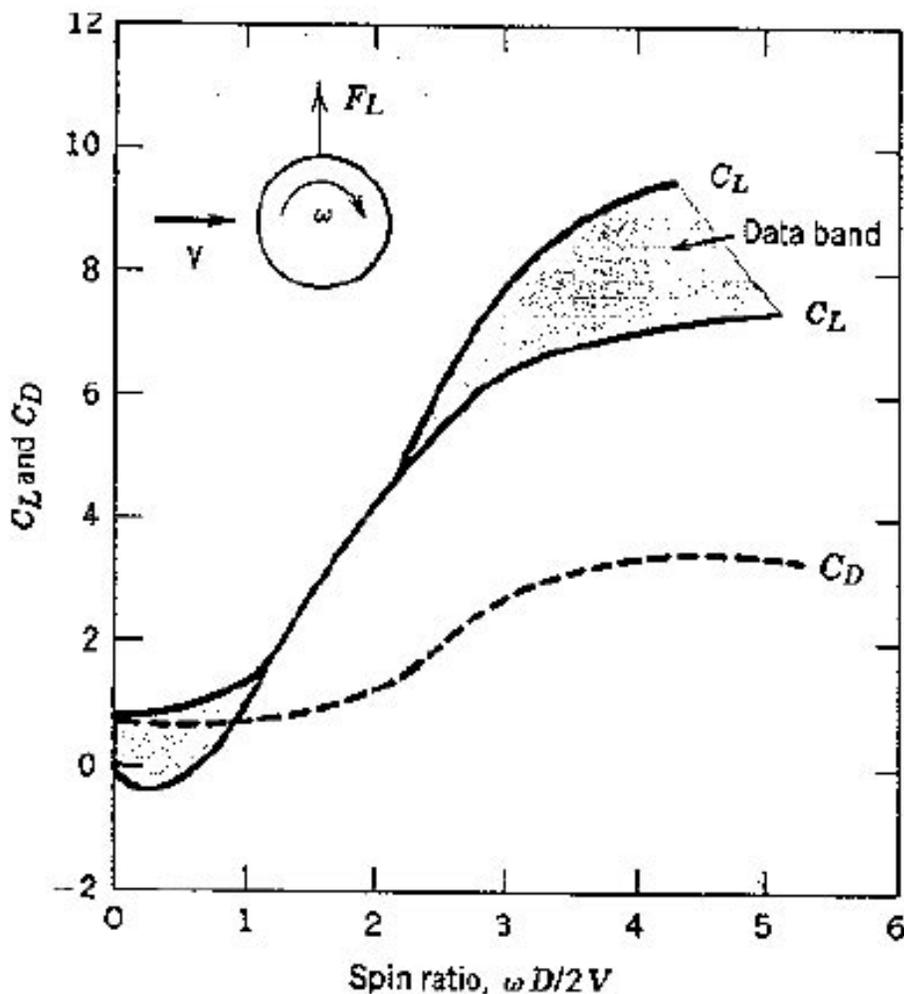


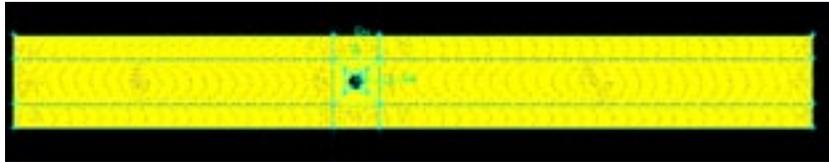
Fig. 9.29 Lift and drag of a rotating cylinder as a function of relative rotational speed: Magnus force. (Data from [32].)

This diagram indicates that lift and drag should be on the same order, as the spin ratio of our problem is $\omega D/2V=1$. $\omega=168$ radians/sec, $V=55.6$ m/sec, and $D=0.66$ m).

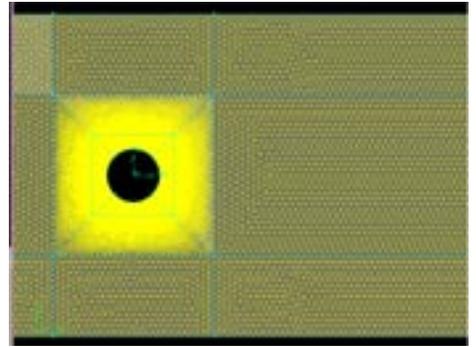
The coefficient of lift is obtained by dividing the lift force by $1/2$ times the density times the velocity squared times the diameter (for this 2D problem), which results in a value of 1250 for our free stream flow.

Source: Louisiana State University Mechanical Engineering website. Original source unknown.

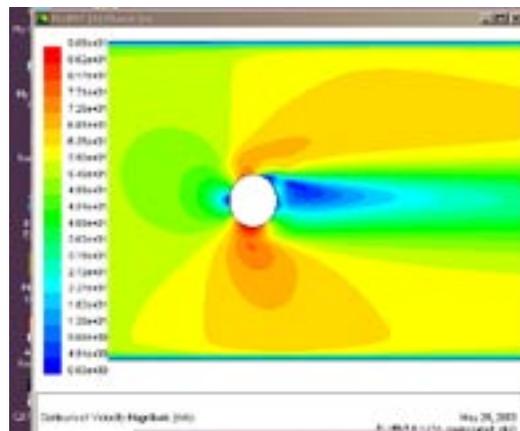
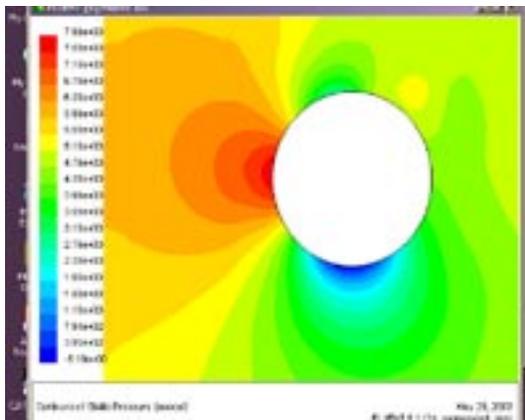
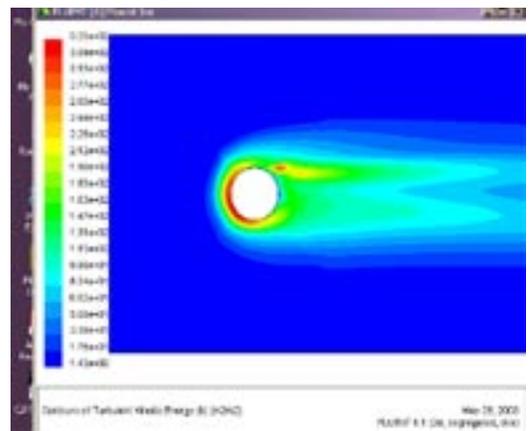
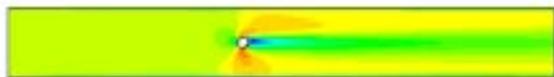
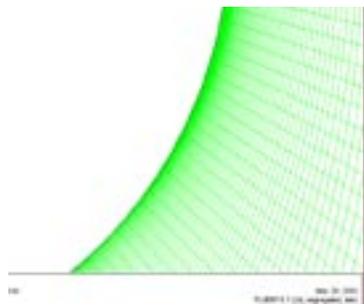
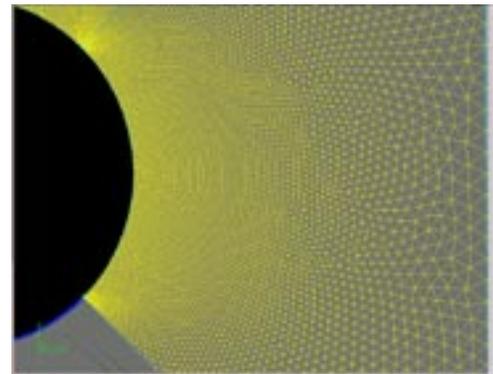
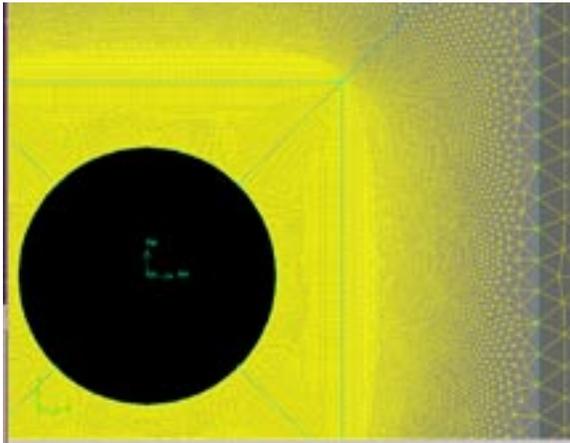
Page 25. Next I tried a variety of new grids, and although the y^+ problem was sometimes solved at the wall boundary, the coarseness and grid gradients in other places caused problems.



Extended inflow and outflow boundaries

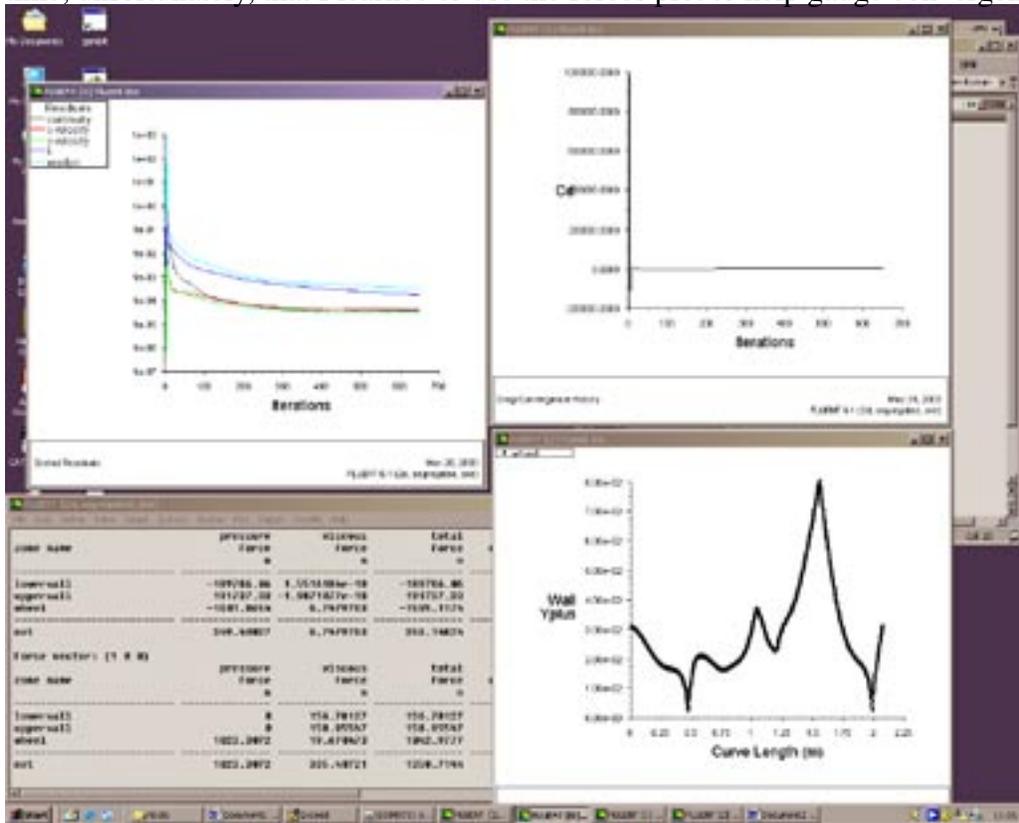


Hybrid triangular center, quad outer grids

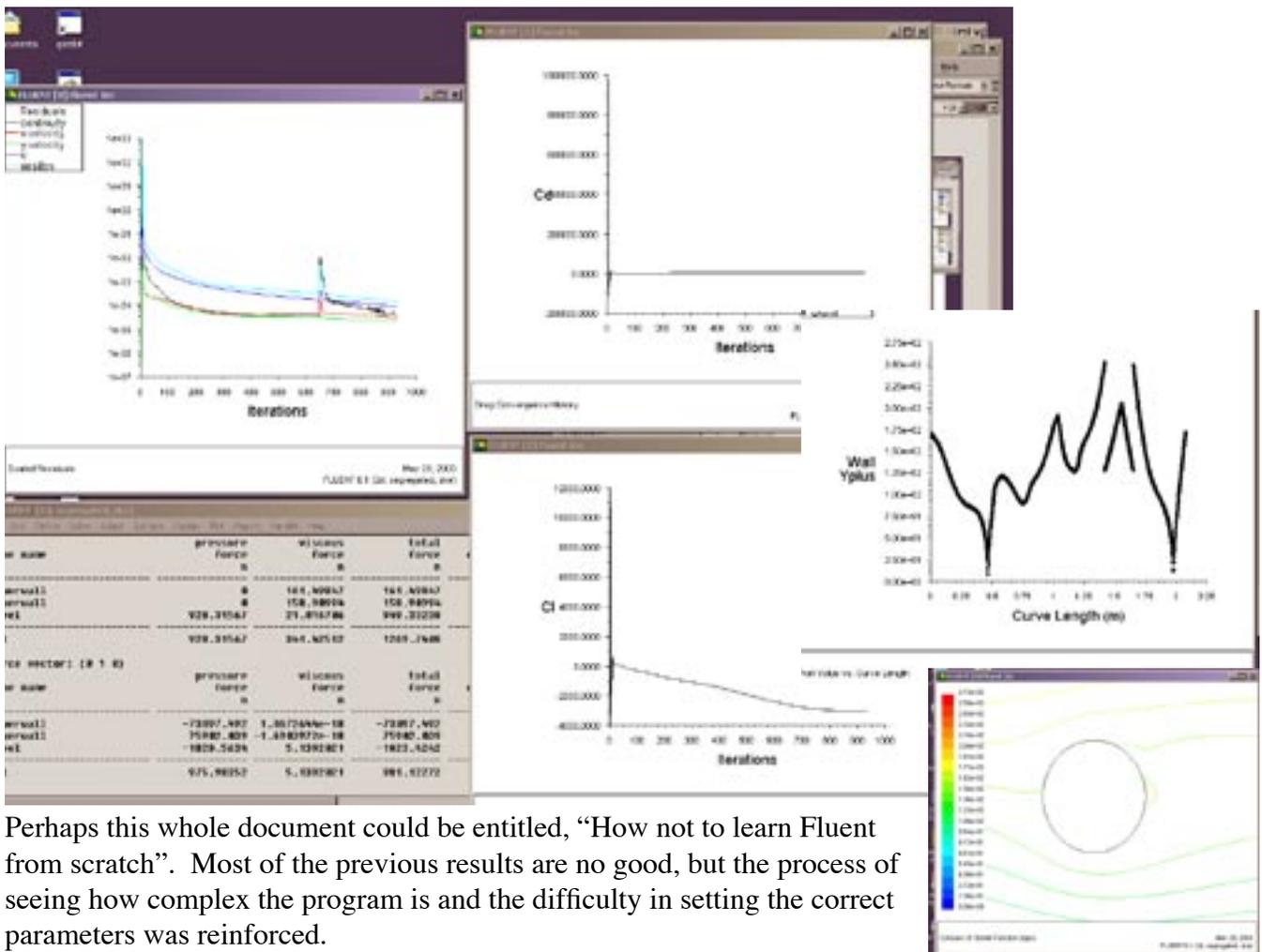


The dense mesh around the circle solved adequately for y^+ but caused undue effects at the high mesh gradient boundaries

Page 26. Some results with a fine but high gradient mesh, with K-e turbulence model. It wasn't until this time, unfortunately, that I learned to use the forces plot to help gauge convergence.

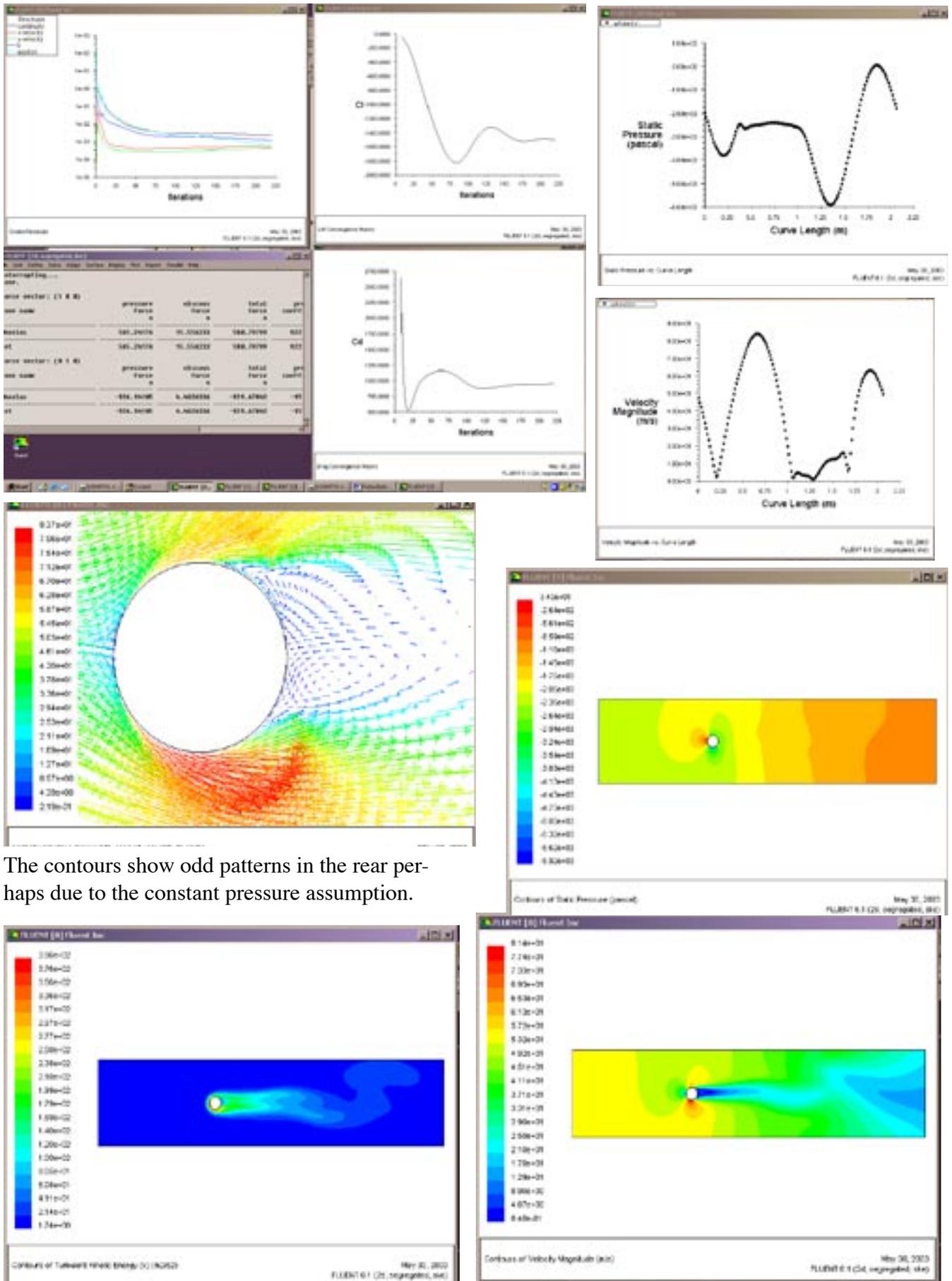


Two runs with very fine mesh around circle, before and after a single y+ boundary adaption.



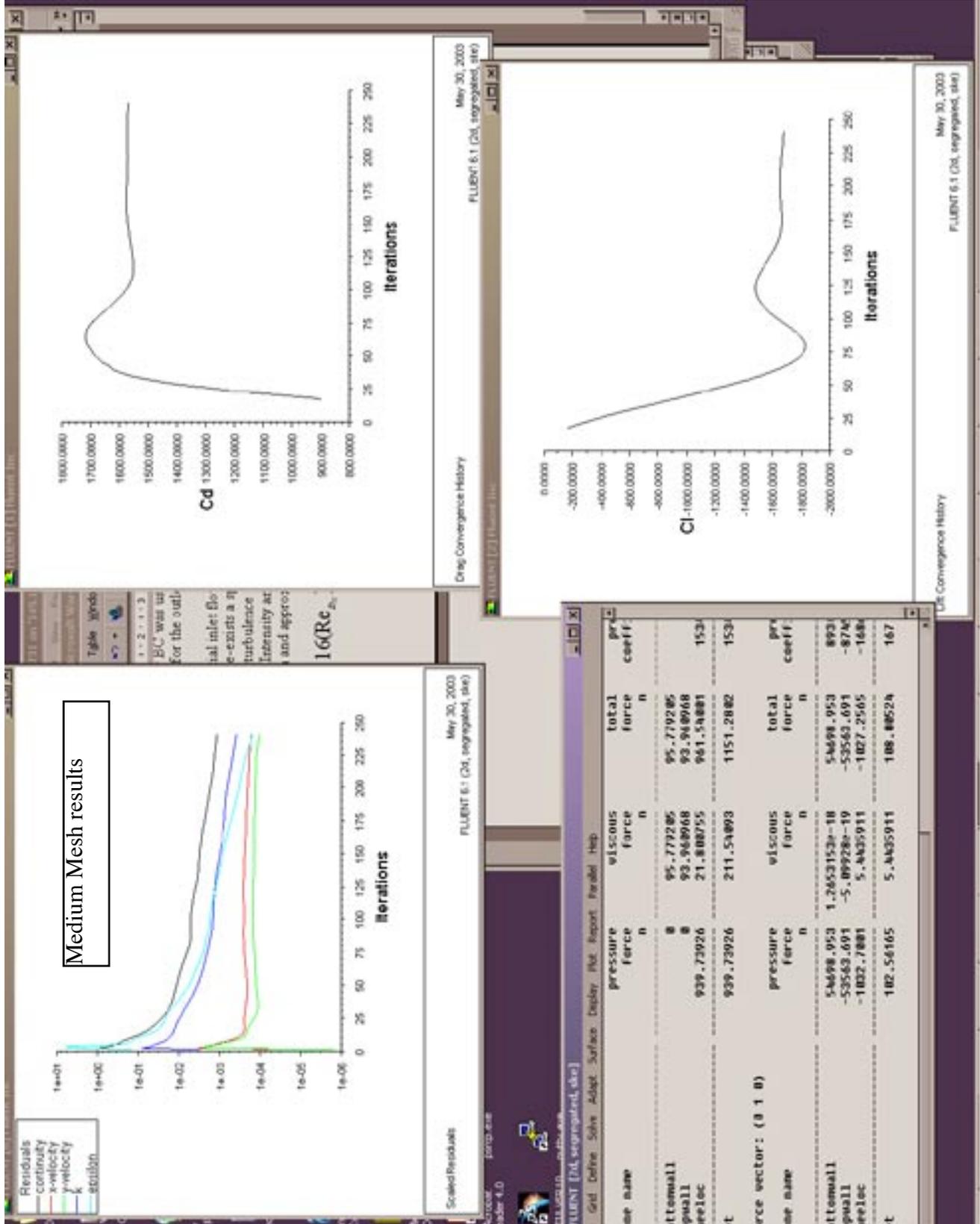
Perhaps this whole document could be entitled, "How not to learn Fluent from scratch". Most of the previous results are no good, but the process of seeing how complex the program is and the difficulty in setting the correct parameters was reinforced.

Page 26. Here, a run with the sidewalls of the wind tunnel changed from WALL to OUTFLOW are presented here.

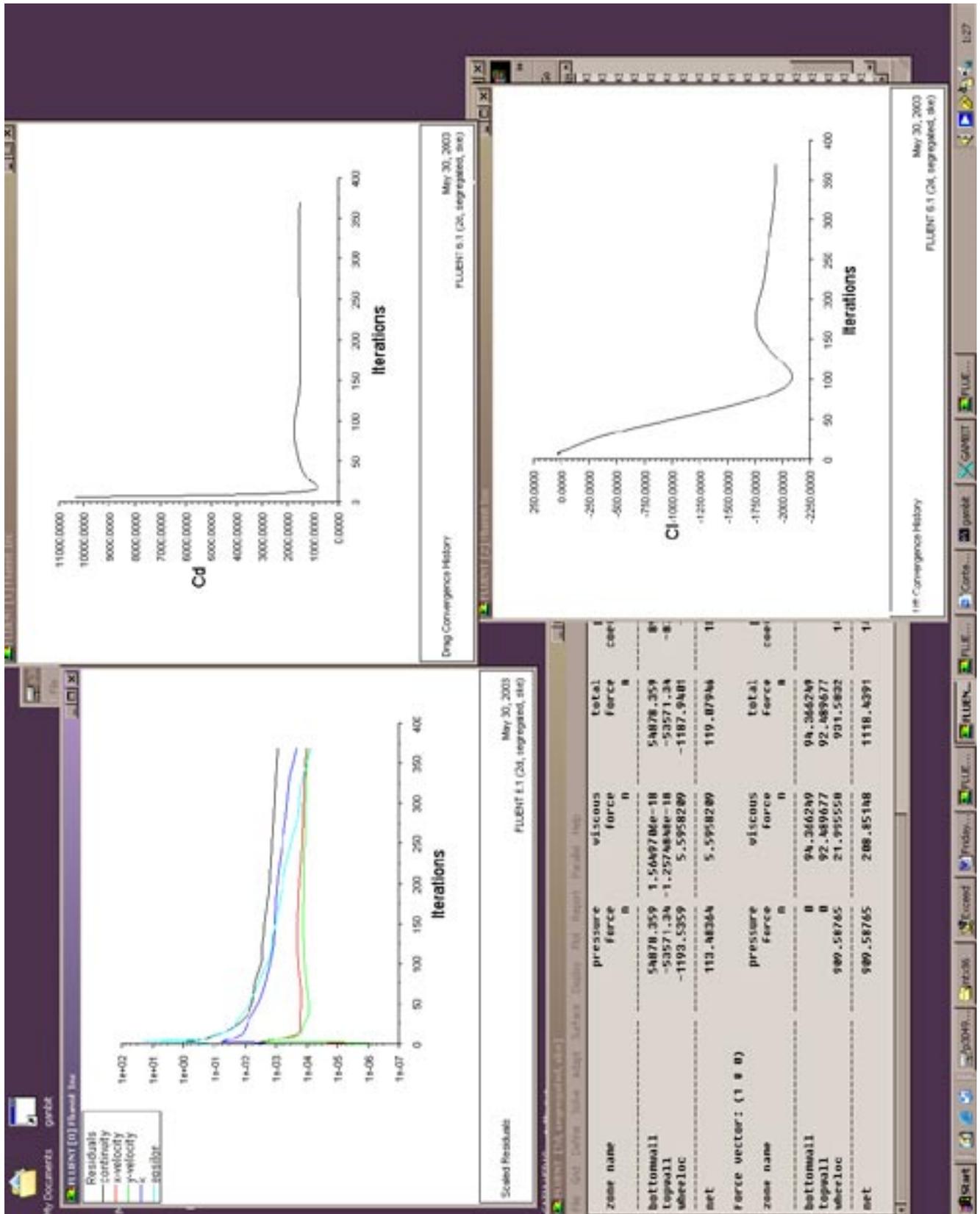


The contours show odd patterns in the rear perhaps due to the constant pressure assumption.

FINAL RESULTS PAGES. The next three pages represent my presentable results. These used the medium, fine, and superfine meshes described on page 16, and were run with the Standard K ϵ model, enhanced wall treatment, initial conditions as specified in the report, and second order discretization. The y^+ values for the mesh cells on the circle were still out of range (3500, 2500, and 1500), but the convergence and contour plots were consistent (see Results p.17-18). To obtain satisfactory y^+ ranges, an entirely new mesh strategy will need to be devised. Additional meshes were run (with 100,000+ nodes) which had y^+ values of 250, but the convergence pattern was not as reassuring as these presented below.



Fine Mesh results. Standard K e model, enhanced wall treatment, initial conditions as specified in the report, and second order discretization. See Results p.16 and following for contour, vector, and XY plots.



“Superfine” mesh results. Standard K e model, enhanced wall treatment, initial conditions as specified in the report, and second order discretization. See Results p.16 and following for contour, vector, and XY plots

